



COMTRAXX® EDGE500IP

Condition Monitor with gateway functionality
for the integration and provision of Bender device data
Software version V5.1.x



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1 General information

1.1 How to use the manual

**ADVICE**

This manual is intended for qualified personnel working in electrical engineering and electronics! Part of the device documentation in addition to this manual is the enclosed supplement "Safety instructions for Bender products".

**ADVICE**

Read the operating manual before mounting, connecting and commissioning the device. Keep the manual within easy reach for future reference.

1.2 Indication of important instructions and information

**DANGER**

Indicates a high risk of danger that will result in death or serious injury if not avoided.

**WARNING**

Indicates a medium risk of danger that can lead to death or serious injury if not avoided.

**CAUTION**

Indicates a low-level risk that can result in minor or moderate injury or damage to property if not avoided.

**ADVICE**

Indicates important facts that do not result in immediate injuries. They can lead to malfunctions if the device is handled incorrectly.



Information can help to optimise the use of the product.

1.3 Service and Support

Information and contact details about customer service, repair service or field service for Bender devices are available on the following website: <https://www.bender.de/en/service-support>.

1.4 Training courses and seminars

Regular face-to-face or online seminars for customers and other interested parties:

<https://www.bender.de/en/know-how/seminars>

1.5 Delivery conditions

The conditions of sale and delivery set out by Bender GmbH & Co. KG apply. These can be obtained in printed or electronic formats.

1.6 Inspection, transport and storage

Check the shipping and device packaging for transport damage and scope of delivery. In the event of complaints, the company must be notified immediately. Please use the contact form at the following address: <https://www.bender.de/en/service-support/take-back-of-old-devices/>.

When storing the devices, observe the information under Environment / EMC in the technical data.

1.7 Warranty and liability

Warranty and liability claims for personal injury and property damage are excluded in the case of:

- improper use of the device
- incorrect mounting, commissioning, operation and maintenance of the device
- Failure to observe the instructions in this operating manual regarding transport, commissioning, operation and maintenance of the device
- unauthorised changes to the device made by parties other than the manufacturer
- non-observance of technical data
- Repairs carried out incorrectly
- the use of accessories or spare parts that are not provided, approved or recommended by the manufacturer
- Catastrophes caused by external influences and force majeure
- Mounting and installation with device combinations not approved or recommended by the manufacturer

This operating manual and the enclosed safety instructions must be observed by all persons working with the device. Furthermore, the rules and regulations that apply for accident prevention at the place of use must be observed.

1.8 Disposal of Bender devices

Abide by the national regulations and laws governing the disposal of this device.



Bender GmbH & Co. KG is registered in the waste from electrical and electronic equipment (WEEE) register under the WEEE number: DE 43 124 402. For more information on the disposal of Bender devices, refer to <https://www.bender.de/en/service-support/take-back-of-old-devices/>

1.9 Safety

If the device is used outside the Federal Republic of Germany, the applicable local standards and regulations must be complied with. In Europe, the European standard EN 50110 applies.



DANGER

Risk of fatal injury due to electric shock!

Touching live parts of the system carries the risk of:

- *Electrocution due to electric shock*
- *Damage to the electrical installation*
- *Destruction of the device*

Before installing the device and before working on its connections, make sure that the installation is de-energised.

Observe the rules for working on electrical systems.

2 Product description

This manual describes

- The COMTRAXX® **EDGE500IP** condition monitor with gateway functionality

The COMTRAXX® EDGE500 series includes a condition monitor with integrated gateway and is integrated into the existing IT structure like any Ethernet-capable device. All Bender devices can be connected via the integrated interfaces. In addition, third-party devices can also be integrated into the system. The measured values, parameters and all other data can be checked, analysed and parameterised via the web interface. Alarms can be reported and visualised. The visualisation application can be used to generate individual overview pages, which are then displayed in a web browser.

Intended use

The EDGE500 converts alarms, measured values and states of the devices into Modbus TCP, Modbus RTU, SNMP, MQTT and HTTP / HTTPS. This enables connection to customer networks as well as visualisation and evaluation with standard web browsers.

It is operated and configured using the web user interface integrated into the device.

Interfaces for acquiring device data

- BCOM
- BMS (intern)
- Modbus RTU
- Modbus TCP

Interfaces for providing device data

- Modbus RTU
- Modbus TCP
- SNMP
- MQTT

The device must always be adapted to the systems and operating conditions on site by means of individual parameterisation in order to meet the requirements of the standards.

Please observe the limits of the application range specified in the technical data. Any other use or use beyond that specified is considered improper.

2.1 Scope of delivery

Included within the scope of delivery

- A condition monitor EDGE500...
- Connector plugs
- A printed quick-start guide
- Safety instructions for Bender products
- The manuals are available as PDF files for download at <https://www.bender.de/en/service-support/download-area/>
- The **configuration file for SNMP** "*comtraxx_mibs.zip*"
The current file is stored on the EDGE500... as a download:
EDGE500... > Menu > Settings > Interface > SNMP > General



*Only registered users can download software.
Please register with your e-mail address.*

2.2 Device features

- Condition monitor for Bender systems
- Integrated modular gateway between Bender systems and TCP/IP enables remote access via LAN, WAN or Internet
- Range of functions adjustable through function modules
- Support of devices that are connected to the internal BMS bus, via BCOM, via Modbus RTU or Modbus TCP
- Individual visualisation can be generated, which is created and displayed via the web browser

2.3 Scope of functions

Basic device (without function modules)

- Condition monitor with web interface
- Interfaces for the integration of devices
 - Internal BMS bus (max. 150 devices)
 - BCOM (max. 255 devices)
 - Modbus RTU and Modbus TCP (max. 247 devices each)
- Gateway to Modbus TCP: Reading the latest measured values, status/alarm messages from addresses 1...5 of the respective interface via Modbus TCP
- Gateway to Modbus RTU: Reading the latest measured values, status/alarm messages from addresses 1...5 of the internal BMS interface via Modbus RTU
- 2 Ethernet interfaces with 10 Mbit/s | 100 Mbit/s | 1 Gbit/s for remote access via LAN, WAN or Internet
- Parameterisation of the individual EDGE500... device parameters
- Time synchronisation for all assigned devices
- 10 data points from third-party devices (via Modbus RTU or Modbus TCP) can be integrated into the system
- 8 galvanically separated digital inputs
- 3 relay outputs

2.4 Function modules

2.4.1 Subsequent installation of function modules

Download the licence files from the Bender homepage.

<https://www.bender.de/en/service-support/licences>

Then activate the function modules in the COMTRAXX® web view:

 **Tools > Service > Function modules**

The button for importing the licence files (.blf) is located below the overview.

2.4.2 Function module "Interfaces"

- Reading the latest measured values, status and alarm messages from all assigned devices. Uniform access to all assigned devices via Modbus TCP over integrated server.
- Reading the latest measured values, status and alarm messages from all assigned devices via internal BMS. Uniform access to all assigned devices via Modbus RTU.

- Control commands: From an external application (e.g. visualisation software or PLC), commands can be sent to BMS devices via Modbus TCP or Modbus RTU.
- Access to alarms and measured values via SNMP (V1, V2c or V3). SNMP traps are supported.
- Alarms and measured values are provided via MQTT.
- 2000 data points from third-party devices (Modbus RTU or Modbus TCP) can be integrated into the system.

2.4.3 Function module "Engineering"

- Display of current measured values, operating/alarm messages and parameters in the system overview
- History memory (20,000 entries)
- Data logger, freely parameterisable (30 x 10,000 entries)
- Creating 100 virtual devices with 16 channels
- Assignment of individual texts for devices, channels (measuring points) and alarms
- Device failure monitoring
- E-mail notification of alarms and system errors to different users
- Creation of device documentation for each device in the system including all parameters and measured values associated with the device, as well as device information such as serial number and software version.
- Creation of system documentation of all devices in the system at once.
- Quick and easy parameterisation of all devices assigned to the gateway using a web browser.
- Creating and restoring device backups for all devices in the system.

2.4.4 Function module "Live View"

- Quick and easy-to-create visualisation of the system. Integrated editor provides access to a variety of widgets and functions.
- Display on up to 50 overview pages on which, for example, room plans can be stored. Navigation within these overview pages is possible.
- Access to all measured values available in the system.
- Buttons and sliders can be used to send test and reset commands and to control external devices via Modbus TCP.

2.4.5 Function module "PROFINET"

- Access to alarms and measured values via PROFINET (from version V 5.1.0).
- 511 PROFINET slots are available.

2.5 Applications

- Optimum display and visualisation of device and plant statuses
- Monitoring and analysing Bender devices and compatible third-party devices
- Customised system overview thanks to a wide range of options
- Selective notification to various users in the event of alarms
- Use of professional visualisation programs through conversion to the Modbus TCP, Modbus RTU, SNMP and MQTT protocols
- Clear setting of device parameters. It is possible to save, document and restore parameters
- Commissioning and diagnosis of Bender systems
- Remote diagnosis, remote maintenance

2.6 Function

The EDGE500 are integrated into the existing IT structure in the same way as PCs. After connection to the network and compatible Bender products, all devices in the system can be accessed from any PC via a web browser. This means that all important system information is directly available. The software is compatible with all standard web browsers.

2.7 Interfaces

EDGE500 communicates with the assigned devices and systems via various interfaces:

- Internal BMS bus (RS-485) for Bender systems such as ISOSCAN® EDS150, LINETRAXX® RCMS460-D or ATICS®. EDGE500 can be operated as a master or as a slave. When operated as a master, requests are answered more quickly.
- BCOM (Ethernet) for Bender systems with Ethernet communication such as ISOMETER® iso685-D
- Modbus RTU (RS-485) for Bender devices such as LINETRAXX® SmartDetect RCMS410 and third-party devices
- Modbus TCP (Ethernet) for Bender devices such as LINETRAXX® PEM353 and third-party devices

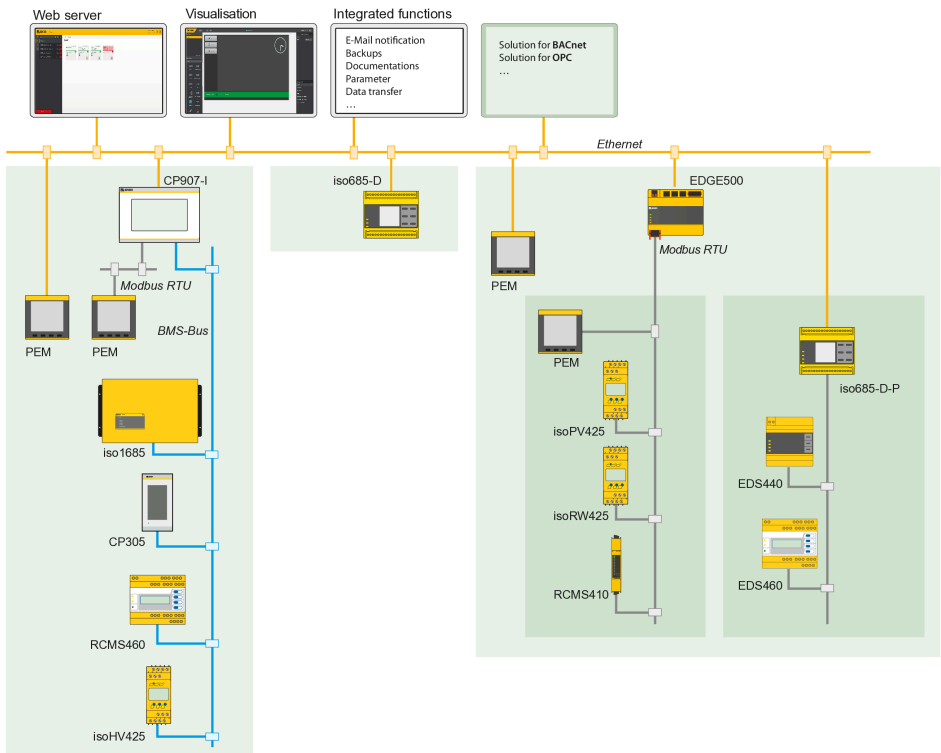


Figure 2-1: Block diagram

2.8 System image

The EDGE500 creates and saves a system image from the communication with the assigned devices. This system image contains all alarms, status information and measured values of the assigned devices.

The EDGE500 combines the information from the different interfaces and makes it available

- for display and configuration via the web interface
- for display and operation via the visualisation
- for transmission to external systems using Modbus TCP, Modbus RTU, PROFINET, SNMP and MQTT

The EDGE500 provides a common user interface for the devices assigned via different interfaces. On this user interface, each device is given an individual address by which it can be identified. BMS, BCOM and Modbus RTU devices receive the appropriate address for their interface. A virtual address is assigned to Modbus TCP devices so that they can be addressed correctly in the system.

3 Mounting, connection and commissioning

TheEDGE500 is normally integrated into existing LAN structures, but can also be operated via a single PC on the Ethernet side.



CAUTION

*If you are familiar with the configuration of computer networks, you can carry out the connection of the EDGE500 yourself. **Otherwise please contact your EDP administrator!***

3.1 Preparation



For initial connection, a basic configuration of the EDGE500 is to be undertaken outside the installation, depending on the specific situation.

1. Have all the questions concerning the installation been discussed with the technician responsible for the installation?
2. Are the settings of the BCOM interface known? System name, subsystem address and device address must be configured.
3. Is the BMS address to be set known? Can EDGE500 be operated as the master (BMS address 1)?

For more detailed information on the topic of BMS, in particular about the wiring of bus devices, please refer to the separate document "BMS bus". You can obtain this document at <https://www.bender.de/en/service-support/download-area/>

4. Modbus RTU: Determine and set baud rate and parity (if the interface is used).
5. Does the computer network have a DHCP server?
If the connected computer network contains a DHCP server, activate the "DHCP" function. The IP address is automatically assigned and displayed. If the computer network does not include a DHCP server, the IP address, network mask (SN) and standard gateway must be specified by the EDP administrator. The IP address has been permanently assigned to the device. Therefore, deactivate the "DHCP" function on the gateway.
6. Ask for the IP address of the NTP server; it is required for the automatic time setting.
7. Are suitable PC hardware and software available for commissioning (PC, tablet, mobile phone with current web browser)?

3.2 Installation and connection



Only skilled persons are permitted to carry out the work necessary to install, put into service and run a device or system.



DANGER

Risk of fatal injury due to electric shock!

Touching live parts of the system carries the risk of:

- Risk of electrocution due to electric shock
- Damage to the electrical installation
- Destruction of the device

Before installing and connecting the device, make sure that the installation has been de-energised. The rules for working on electrical systems must be observed.



DANGER

Mortal danger and risk of irreparable damage due to moisture!

Install device such that it is protected against moisture.



CAUTION

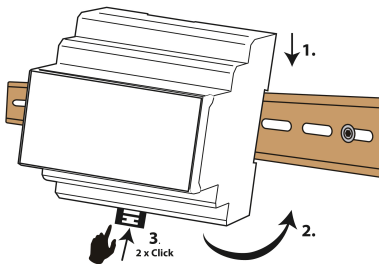
Pay attention to installation location

Operation of the device is only permitted in operating locations with **restricted access!** This can be installation in a switch cabinet, for example.

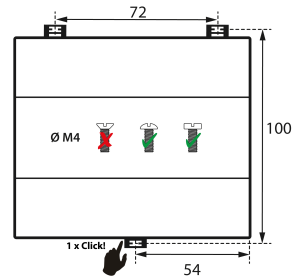
3.2.1 Mounting the device

The device is suitable for the following types of installation:

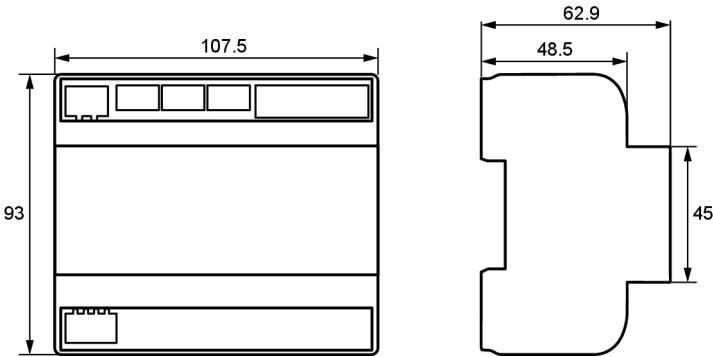
- Snap-on mounting on a DIN rail according to IEC 60715 or
- Screw mounting using 3 x M4



Snap-on mounting on a DIN rail according to IEC 60715

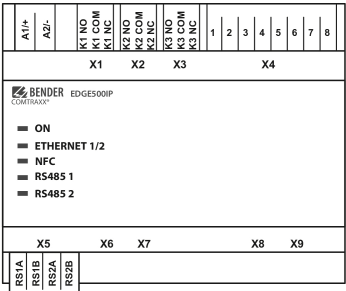


Screw mounting using 3 x M4

Dimension diagram (mm)**3.2.2 Connecting the device**

For UL applications, the following must be observed:

- Maximum ambient temperature: 55 °C
- Use 60/75°C copper lines only



Element	Explanation	Clamp
A1/+; A2/-	Power supply	
Plug X1	Relay output K1	K1 NO K1 COM K1 NC
Plug X2	Relay output K2	K2 NO K2 COM K2 NC
Plug X3	Relay output K3	K3 NO K3 COM K3 NC

Element	Explanation	Clamp
Plug X4	Digital inputs	IN1...8
Plug X5	RS-485 interfaces	RS1A RS1B RS2A RS2B
Plug X6	Ethernet interface 1	ETH1
Plug X7	Ethernet interface 2	ETH2
Plug X8	USB-C interface 1	USB1
Plug X9	USB-C interface 2	USB2

Make the connection as follows:

- 1. BMS bus connection
Connect the terminals **RS2A** and **RS2B** to the BMS bus (A to A, B to B). If the EDGE500 is located at one end of the BMS bus, you must switch on the termination in the COMTRAXX® menu.
- 2. Modbus RTU connection
Connect the terminals **RS1A** and **RS1B** to the Modbus RTU (A to A, B to B). If the EDGE500 is located at one end of the bus, you must switch on the termination in the COMTRAXX® menu.
- 3. Ethernet connection ((BCOM, Modbus TCP, SNMP, MQTT)
Both interfaces can be configured individually. Plug the Ethernet cable (RJ45) into ETH1 or ETH2 of the EDGE500. The device can then be integrated into a network. A shielded Ethernet cable of category 5 (Cat. 5) or better must be used.
- 4. Relay output connection

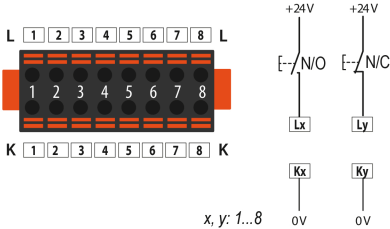


$K...NO + K...COM > N/O$ principle

$K...NC + K...COM > N/C$ principle
- 5. Connection of digital inputs
- 6. Connect power supply
Connect terminals A1/+ and A2/- to a power supply.

3.2.3 Digital inputs

EDGE500-devices have 8 parameterisable digital inputs. The settings are made via the COMTRAXX® user interface in a browser (see chapter “Digital inputs”, page 27).

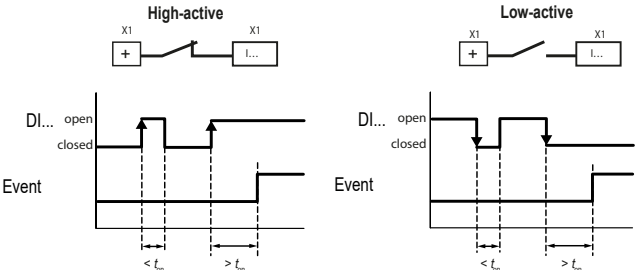


Menu > Settings> Digital Input 1 - 8

The following functions can be defined to the digital inputs IN1...8:

Parameter	Options/Setting range	
Mode	High-active Low-active Impuls (High-active) Impuls (Low-active)	
Measurement type	Operating message Alarm Error(s)	
t_{on}	Response delay	0 s...10 minutes
t_{off}	Switch-off delay	

An event is executed when the digital input experiences an edge change. The edge change must be present at least for the set response delay t_{on} , otherwise it is ignored.



3.2.4 Relays

EDGE500 has three relays (changeover contacts).

Relay wiring



N/C

N/O

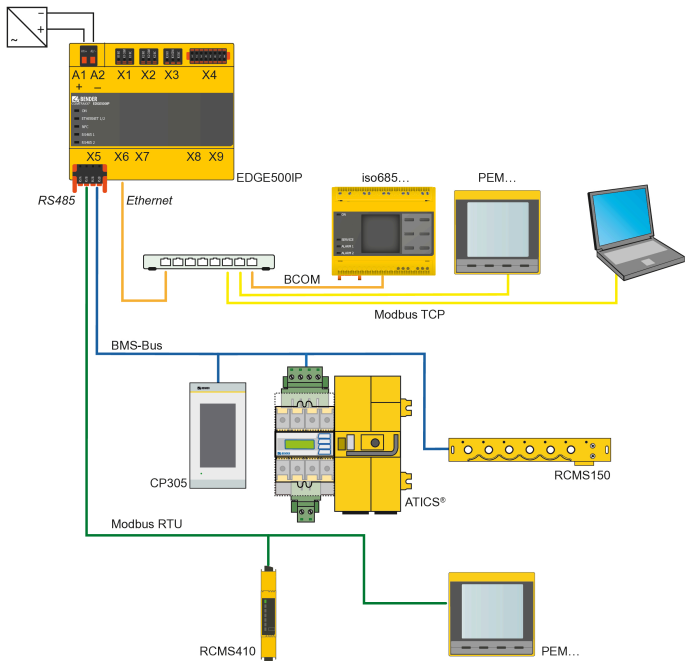
N/C operation contacts ...NC - ...COM
(The alarm relay is energised during normal operation)

N/O operation contacts ...NO - ...COM
(The alarm relay is de-energised during normal operation)

The three relays are parameterised in the device menu (see chapter “Relay”, page 28).

3.2.5 Connection diagram

Connection diagram EDGE500 (Example)



3.3 Display and control elements

A1+	A2+	K1 COM	K1 NC	K2 NO	K2 COM	K2 NC	K3 NO	K3 COM	K3 NC	1	2	3	4	5	6	7	8
X1				X2			X3			X4							
 BENDER EDGESQUIP COMPAQ																	
■ ON ■ ETHERNET 1/2 ■ NFC ■ RS485 1 ■ RS485 2																	
X5				X6			X7			X8				X9			
RS1A	RS1B	RS2A	RS2B														



LED	Funktion
ON	"ON" LED: Flashes during the start process. The LED lights continuously as soon as the device is ready for operation.
ETHERNET 1/2	LEDs indicate activity on the various interfaces. <i>Note: NFC in preparation</i>
NFC	
RS485 1	
RS485 2	

3.4 Commissioning the device

1. Switch on the supply voltage:
When the device is supplied with power, all LEDs light up briefly. During the start process the "ON" LED flashes. After a successful start, the "ON" LED then illuminates continuously. The device is now ready for operation.

The EDGE500 has 2 Ethernet interfaces (ETH1 and ETH2). Please note that **only ETH1 is BCM-capable and can be used to integrate Bender devices into the network**. ETH2 connects the customer network, for example the building management system, to the network.

2. Start web user interface:
 - Open a web browser.
 - Type the following IP address to open the web interface of the EDGE500:

ETH1:

If your PC is in a 192.168.0.0 IT subnet, you can reach the via the factory-set IP address 192.168.0.254.

ETH1|ETH2:

If your PC is in a different subnet, you must disconnect the PC from your network. Connect the directly to your PC. Open the web user interface using the second pre-defined IP address:

ETH1: 169.254.0.1 | ETH2: 169.254.0.2

For this purpose, DHCP must be enabled on the PC.

In the web user interface, the IP address of the can be set as required.

3. Configure:
As a minimum, configure all address parameters for the EDGE500.
4. **ETH1** only:
Always configure the BCOM interface (system name, subsystem, device address).



Risk of duplicate addresses if BCOM system name is not changed.

The factory setting for the system name on all Bender BCOM devices is "SYSTEM". If several systems are established in the same network, there is a risk that addresses will be assigned more than once.

Therefore, always give each system a new BCOM system name during commissioning.

If several EDGE500 are to communicate in one system, the system name must be selected uniformly and only the subsystem address must be separated.

5. Integrate devices into the system:
 - **ETH1** only:
BCOM devices are detected automatically
 - **ETH1|ETH2:**
Modbus devices need to be configured. This is done in the web interface at
 **> Device management> Modbus devices > Manage devices**

6. Check connection
Connect the EDGE500 to the network again. Start the web user interface. All other settings (individual texts, e-mail notifications, ...) can now be made.

3.5 Factory settings for addresses

The EDGE500 is supplied with the following factory settings:

Parameter	Factory setting	
	ETH1	ETH2
IP address	192.168.0.254	10.0.0.254
Second fixed IP address (e.g. for commissioning)	169.254.0.1	169.254.0.2
Net mask	255.255.0.0	255.0.0.0
Standard gateway	192.168.0.1	10.0.0.1
DNS	192.168.0.1	10.0.0.1
DHCP	off	off
t _{off} (Timeout for DHCP address assignment)	30 s	30 s
BMS address	1	-
BCOM system name	SYSTEM	-
Subsystem address	1	-
BCOM device address	0 (= off)	-

The settings can be changed using the web user interface.

4 Web user interface

The web user interface of the device enables access via LAN, WLAN or the Internet. It provides a uniform display of Bender devices that are connected to:

- the internal BMS bus
- the BSC bus
- BCOM
- Modbus RTU
- Modbus TCP

Each interface has its own address range. Each device is given its own individual address by which it can be identified.

4.1 Functions of the web user interface

- Bus overview of the associated devices
 - Indicating alarms and measured values
 - Display by interface or subsystem
 - Setting, displaying and evaluating the history memory and data loggers
 - Graphical display of measured values
 - Setting device parameters
 - Device failure monitoring
 - Saving settings as "backup" and restoring values again
 - Documenting settings and measured values
 - Assigning individual texts for devices, measuring points (channels) and alarms
 - E-mail notifications to different user groups according to a time-controlled schedule in the event of alarms and system errors. The sender's e-mail address can be entered.
 - Display of virtual devices. A virtual "measuring point" is obtained by logically or numerically evaluating measured values of "real" devices connected to the gateway.
- Management of Modbus devices
 - Adding/deleting devices to/from the bus overview
 - Creating a template with selected measured values
- Visualisation
 - Fast, simple visualisation can be configured in its own editor without programming knowledge
 - Measured values, alarms, buttons, etc. can be arranged and displayed in front of a graphic (system diagram, room plan) using various widgets
 - Multiple dashboards configurable. Navigation between these is possible
- From an external application (e.g. visualisation software), commands can be sent to BMS devices. The "Modbus control commands" menu provides Modbus control commands for selected BMS commands.
- Graphical display with scaling of the time axis for the data loggers of the gateway and compatible Bender devices.



The planning and creation of individual visualisations for hospital projects are handled by the projects department on request.

4.2 Software products used

Select  **Tools > Information > Software information**, to display the used software products.

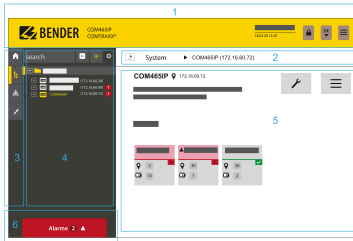
4.3 Browser configuration

The latest version of all common standard browsers like Firefox, Chrome or Microsoft EDGE can be used.

To use the functions of the web user interface, JavaScript has to be activated. The pop-up blocker should be deactivated for the IP address of the COMTRAXX® device.

4.4 Home page COMTRAXX® user interface

1. Open an Internet browser.
2. Enter the IP address of the COMTRAXX® device in the address line (example: <http://172.16.60.72>).



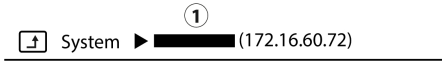
- 1 Headline
- 2 Path display
- 3 Navigation
- 4 Subnavigation
- 5 Content area
- 6 Alarm overview

4.4.1 Headline



- 1 Clicking the logo: Return to home page
- 2 Used device: Device type
- 3 Used device: **System name > Subsystem > Device address**
Date and time of the device
- 4 The symbol indicates that the web user interface is protected by a password. Click the symbol and then click **Login** to enter the user name and password.
- 5 Language selection
- 6 Open/close navigation (button only available in small browser window)

4.4.2 Path display (breadcrumb navigation)



1= Device

The path display always shows in which part of the system you are currently located in the content window.

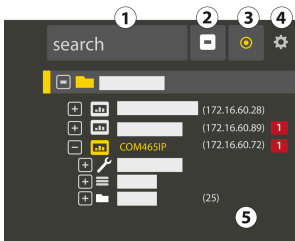
4.4.3 Navigation

	Menu	Description
	Start	Display of information about the device and the software. Please have this information to hand if you need to contact us for assistance by telephone.
	System overview	The system overview shows all devices in the system either by subsystem or by interface. Pending alarms and operating messages are displayed and the respective devices can also be configured.
	Alarms	Display of all pending alarms and data of the devices sending an alarm
	Tools	Functions that affect the entire system

The navigation symbols are permanently visible on the left side. Even if a random submenu of the web user interface is open, you can navigate to one of the four areas by clicking the respective symbol.

4.4.4 Subnavigation

The system overview is displayed in the subnavigation.



Legend

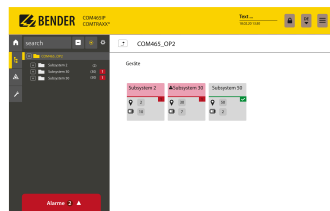
1. Full text search in the system for device names or menu entries. Matches are highlighted in yellow.
2. Close unfolded tree in the subnavigation
3. Fold out automatically: When enabled (= yellow), the displayed contents of the content area are shown in the subnavigation with automatically unfolding device tree in addition to the path display. Path display and content area are always synchronous. When disabled (= white), the subnavigation is not adapted to the path display or the current content area.

- 4. - Select display by subsystems or by interfaces
 - Display time stamp of the measured values
 - Show inactive channels
 - Configure the line height of the entries.
5. The number in brackets (here: 25) indicates the set bus address.

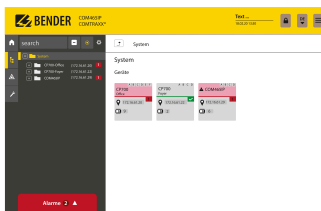
 *The display by subsystem or interface is possible independently of the configured Modbus image V1 or V2.*

4.4.5 Content area

Display of the system, alarms and entries for the tools .



Content area of the system display by **subsystem**



Content area of the system display by **interface**

4.4.6 Overview of pending alarms



 **Clicking the alarm overview:** List of pending alarms
Clicking on the list: Details about the alarms in the content area

4.5 Password protection

Password protection: Access to the web interface can be restricted for different user groups.

 **CAUTION**
Risk of damage to equipment due to unauthorised access
The password protection for the EDGE500 protects against unauthorised access to a limited extent only. Attackers from the Internet may still be able to read data and change settings.
It is absolutely necessary that:

- The network is separated from the Internet .
- Common security mechanisms are applied (firewall, VPN access).

Further Information

“Configure password protection in the COMTRAXX® user interface”, page 31

4.6 Making settings on the device

Changes must be saved before leaving the respective mask. Otherwise they are discarded.

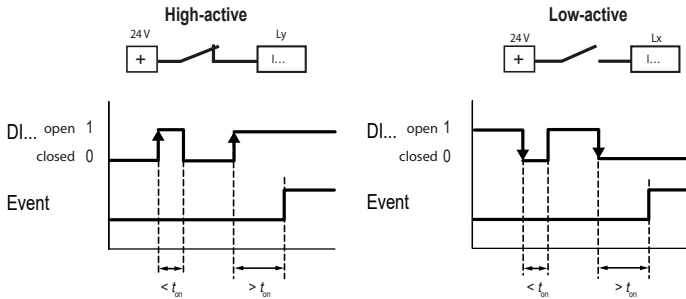
4.6.1 Digital inputs

Menu > Settings > Digital inputs 1 - 8

For each of the 8 digital inputs IN1...8, the following can be defined:

Parameter	Options/Setting range	
Mode	High-active Low-active Impuls (High-active) Impuls (Low-active)	
Measurement type	Operating message Alarm Error(s)	
t_{on}	Response delay	0 s...10 minutes
t_{off}	Switch-off delay	

An event is executed when the digital input experiences an edge change. The edge change must be present at least for the set response delay t_{onr} otherwise it is ignored.



4.6.2 Relay

Menu > Settings > Relay

Setting options	Options	Explanation
Relay mode	N/O	Normally Open
	N/C	Normally Closed
Relay mode	Cont.	Relay remains permanently energised.
	Imp.	Relay is energised for one pulse.
	Flash	Relay switches several times between active and inactive.
Timer	100 ms...2 s	"Imp." mode: impulse time "Flash" mode: cycle time
PowerOn	off	Relay is deenergised during device start.
	on	Relay is energised during device start.
	PowerOff	During device start the relay takes on the same state it had when the supply voltage was switched off.

4.6.3 Interface

Menu > Settings > Interface

The required parameters for each connected interface are set here:

- BCOM
- Ethernet
- BMS/BSC
- Modbus
- SNMP
- MQTT
- PROFINET
- POWERSCOUT®

4.6.4 Edit texts

Menu > Settings > Edit texts

The individual device and channel texts of the COMTRAXX® device are configured here. The data logger texts can also be edited.

Setting options	Setting	Description
Channels	Digital input 1...8	Descriptive text and alarm text
	Relay 1...3	Descriptive text
	Timer 1...12	Descriptive text
Device	Device name	
	Message in case of device failure	

Setting options	Setting	Description
Data logger	Data logger1...30	Descriptive text

4.6.5 E-mail

Menu > Settings> E-mail > Profile

The following is set for 5 different profiles:

Setting options	Setting for.../Description
Settings	Profile Active Server Timeout Port Encryption Check certificate User Password Send test e-mail Configure e-mail
E-mail	Language Sender To (= addressee) Subject Messenger header Message footer E-mail in the event of prewarning E-mail in the event of test alarm System monitoring ¹⁾ Send test e-mail Configure e-mail
Test	Send test e-mail to check all settings

- 1) Activates e-mail monitoring for the entire system. Individual e-mail configurations are not taken into account, but all measured value alarms and device failures are reported.

4.6.6 History/Logger

Menu > Settings > History/Logger

Setting options	Setting for.../Description	
History	History content	Complete system
		Own device and all subdevices
	Delete	
Data logger 1...30	Name	
	Path	
	Status	on, off
	Percentage change	off, 1...99 %
	Trigger	off, 15 minutes ...7 days
	Absolute change	off or precise limit value
	Overwrite	yes, no
	Delete	
BMS recording		off, 1...7 days

4.6.7 Clock

Menu > Settings > Clock

Setting options	Setting for.../Description
Summer time	off, on, CEST, DST
UTC offset	
NTP	off, on
NTP server	

4.6.8 Security

Menu > Settings > Security > Password

Password protection can be configured for the **User** and **Administrator** roles. This controls access to the web interface.



CAUTION

Risk of damage to equipment due to unauthorised access

The password protection for the EDGE500 protects against unauthorised access to a limited extent only. Attackers from the Internet may still be able to read data and change settings.

It is absolutely necessary that:

- *The network is separated from the Internet .*
- *Common security mechanisms are applied (firewall, VPN access).*

Factory settings: User groups

Role	Status	Password	User name	Read access	Write access
Administrator	enabled	default	admin	allow	allow
User	enabled	default	user	allow	deny
not logged in	-	-	-	deny	deny

The default user names and authorisations ("admin, read and write" and "user, read only") cannot be changed.

Setting options for role	Range of values				
Status	enabled, disabled				
Password	A...Z	a...z	0...9	-	_

4.6.9 Factory settings

Menu > Settings > Factory setting

When resetting to factory settings, all settings, parameters, data logger and history memory are reset. It can be specified that Ethernet settings are not affected.

4.6.10 Software update

The EDGE500 software is continuously being developed. To use the latest software on your devices, you have the option of updating your devices regularly. You can update both the EDGE500 and COMTRAXX® devices connected via Modbus.



It is recommended that you back up your data before updating.

Download the latest software version from the Bender homepage and save it on your PC.

Update EDGE500

You can find the update option in the web browser navigation under

 Tools > Service > Update. Follow the individual steps.

Update COMTRAXX® devices connected via Modbus

You will find the update option in the web browser navigation under  **Tools** > **Modbus Devices** > **Manage Devices** > (**Functions** >  **Update**). Follow the individual steps.

4.7 Device failure monitoring

Specify which devices are to be monitored for a device failure. There are various ways to do this:

a)

Select the device to be monitored in the  **System overview** and activate or deactivate the bell in the respective tile of the device. The overview of the selected devices can be found under  **Tools** > **Monitoring** > **Device failure monitoring**.

b)

Manually add or delete the devices to be monitored under  **Tools** > **Monitoring** > **Device failure monitoring**.

c)

Under  **Tools** > **Monitoring** > **Device failure monitoring** > **Import actual state** (button in the footer), add all active devices of the entire system to the monitoring. The list can be edited to remove unnecessary devices from the device failure monitoring.



Device failure monitoring is only active on the COMTRAXX® device on which it has been individually configured.

Other COMTRAXX® devices in the system are not affected by these settings and use their own device failure monitoring.

This means that device failures in the system can only be reported on the COMTRAXX® devices on which they were previously configured.

5 Virtual devices

The concept of virtual devices involves combining existing measurements with other measurements in such a way that additional values, operating or alarm states can be displayed. Combine up to 26 measurements with numerical and logical operators to create a new "virtual" measuring point. Each of these measuring points uses one channel. A virtual device consists of a maximum of 16 channels. Virtual devices are treated like real devices and are fully integrated into the Bender system: All calculated values

- can be stored in a data logger,
- are available via Modbus,
- can be displayed in a visualisation.

5.1 Application possibilities

Alarms and warnings

Alarms and warnings can be configured for Modbus devices. Through virtual devices, user-defined warning limits can be set for devices that do not offer this option (e.g. PEMs). Each generated warning appears in the warning history and can be used to send an e-mail notification.

Device failure monitoring

In large buildings with many devices installed in a production hall, department or floor, virtual devices simplify simultaneous monitoring for device failure. It allows narrowing down the location of the failure and enables fast intervention.

Converting to BMS bus (mirroring)

Operating states of the virtual devices can be transmitted via BMS bus even if the real devices have no BMS interface. For this purpose, the virtual devices are "mirrored" to the BMS bus. The states of the measuring points (channels 1...12) are transmitted during the channel query of the BMS master.

 Only **operating states** are transmitted via the BMS bus (No alarm, Prewarning, Alarm). Specific measured values cannot be transmitted.

5.2 Managing virtual devices

Path: Tools > Device management > Virtual devices

5.2.1 Virtual devices: Overview list/Main page

Address

Device addresses: 1...255

Alarm

Current operating state of the virtual device (prewarnings are displayed as alarms)

☒ No Alarm ☐ Alarm

Device name

 Virtual devices are always named "VD700..."

Mirrored

When enabled, the operating states of channels 1...12 of the virtual device are transmitted via BMS bus.

5.2.2 Editing a virtual device



Device address, device name and BMS mirroring can be edited.

5.2.3 Editing channels



In the channel overview, the 16 possible channels are displayed with the following information:

- Current operating state ( no alarm  Prewarning  Alarm)
- Individual text for prewarning or alarm
- General and individual channel description
- Current measured value
- Defined formula

In the overview, channels can be created or edited via . Channels can be deleted via .



Refer to the "Legend and examples" tab for assistance.

5.2.4 Deleting a device



A virtual device can be deleted via the bin.

5.2.5 Adding a virtual device

Use the button in the footer to add virtual devices.



The number of virtual devices that can be created depends on the COMTRAXX® device used or its active function modules.

Device address

Select a free bus address from the drop-down menu.



Virtual devices are treated like real devices. Therefore, addresses must not be assigned twice!

Device name

Assign a name to the virtual device.



Virtual devices are always named "VD700...". In addition, an individual name can be assigned.

Mirroring to BMS

If operating states are to be transmitted via BMS, this can be set here.



Virtual devices are treated like real devices. Therefore, addresses must not be assigned twice!

6 Modbus TCP server



*The Modbus TCP addresses 1...10 are provided with the basic device.
Function module "Interfaces" is required to use the entire address range.*



Help tools that provide comprehensive information about Modbus can be found in the web user interface under



Tools > Service > Modbus

- Generate control commands for BMS
- Display information on all available Modbus registers
- Generate Modbus documentation of all available Modbus registers of the connected devices

The Modbus TCP server supports the following function codes:

- Function code **0x03** (Read Holding Registers)
- Function code **0x04** (Read Input Registers)
- Function code **0x10** (Preset Multiple Registers)

The Modbus TCP server generates a function-related response to requests and sends it back to the Modbus TCP client.

6.1 Modbus requests

The required data of the system image are read from the COMTRAXX® device using the function codes **0x03** and **0x04**. For this purpose, the start address and the number of the registers to be read have to be entered. In addition, registers can also be written using function code **0x10**.

6.1.1 Example for function code 0x03

Configuration

- COMTRAXX® device in subsystem 1 with BCOM and BMS address 1
- BMS device on BMS interface with address 2

Task

- Read register 0x05 10 of the BMS device

Byte	Name	Bender modbus image V1	Bender modbus image V2
Byte 0, 1	Transaction identifier	0x00 00	0x00 00
Byte 2, 3	Protocol identifier	0x00 00	0x00 00
Byte 4, 5	Length field	0x00 06	0x00 06
Byte 6	Unit-ID	0x02 Device address assignment (0x02 corresponds to the device address 2 of the subsystem)	0x05 (address assignment via device assignment (0x05 = unit ID assigned by way of example for the device in the Modbus device assignment)
Byte 7	Modbus function code	0x03	0x03
Byte 8, 9	Register start address	0x05 10	0x05 10
Byte 10, 11	Number of words	0x00 01	0x00 01

6.1.2 Example for function code 0x04

Configuration

- COMTRAXX® device in subsystem 1 with BCOM and BMS address 1
- BMS device on BMS interface with address 2

Task

- Read measured value from channel 1 of the BMS device

Byte	Name	Bender Modbus image V1	Bender Modbus image V2
Byte 0, 1	Transaction identifier	0x00 00	0x00 00
Byte 2, 3	Protocol identifier	0x00 00	0x00 00
Byte 4, 5	Length field	0x00 06	0x00 06
Byte 6	Unit-ID	0x01 Address assignment of the subsystem (0x01 corresponds to subsystem address 1)	0x0A Address assignment of the interface 0x0A = interface internal BMS
Byte 7	Modbus function code	0x04	0x04
Byte 8, 9	Register start address	0x02 10 Start register (0x02 = device address 2; 0x10 = start register for channel 1)	0x01 62 Start register (measured value channel 1)
Byte 10, 11	Number of words	0x00 02	0x00 02

6.1.3 Example for function code 0x10

Configuration

- COMTRAXX® device in subsystem 1 with BCOM and BMS address 1
- BMS device on BMS interface with address 2

Task

- Write value = 100 to register 0x05 10 of the BMS device

Byte	Name	Bender Modbus image V1	Bender Modbus image V2
Byte 0, 1	Transaction identifier	0x00 00	0x00 00
Byte 2, 3	Protocol identifier	0x00 00	0x00 00
Byte 4, 5	Length field	0x00 06	0x00 06
Byte 6	Unit-ID	0x01 Address assignment of the subsystem (0x01 corresponds to subsystem address 1)	0x0A Address assignment of the interface (0x0A = interface internal BMS)
Byte 7	Modbus function code	0x10	0x10
Byte 8, 9	Register start address	0x05 10	0x05 10
Byte 10, 11	Number of registers	0x00 01	0x00 01
Byte 12	Number of registers x2	0x02	0x02
Byte 13 ... xx	Values	0x64	0x64

6.2 Modbus responses

The responses consist of 2 bytes per register. The byte sequence is MSB (Most Significant Bit, Big Endian) first.

6.2.1 Responses for function code 0x03 and 0x04

Byte	Name	Example
Byte 1...6	Identical with request	
Byte 7	Modbus function code	0x03 or 0x04
Byte 8	Byte count	0x04
Byte 9, 10	Value register 0	0x12 34 (fictitious value)
Byte 11, 12	Value register 1	0x23 45 (fictitious value)

6.2.2 Responses for function code 0x10

Byte	Name	Beispiel
Byte 1...6	Identical with request	
Byte 7	Modbus function code	0x10
Byte 8, 9	Register start address	0x12 34 (fictitious value)
Byte 10, 11	Number of registers	0x00 12 (fictitious value)

6.2.3 Exception code

If a request cannot be answered for whatever reason, the Modbus TCP server sends an exception code with which possible faults can be narrowed down.

Overview of exception codes

Exception code	Description
0x01	Impermissible function
0x02	Impermissible data access
0x03	Impermissible data value
0x04	Slave device error
0x05	Acknowledgement of receipt (response delayed)
0x06	Request not accepted (repeat request if necessary)
0x08	Memory: Parity Error
0x0A	Gateway path not available
0x0B	Gateway error

Structure of the exception code

Byte	Name	Example
Byte 1...6	Identical with request	
Byte 7	Modbus function code	0x84
Byte 8	Exception code	

6.3 Modbus system image

The COMTRAXX® device stores a system image in the internal memory. This shows the present values and states of all devices that are connected via the device. The system image depends on which Bender Modbus image (V1 or V2) is active on the COMTRAXX® device.

Starting from COMTRAXX® version V4.00, address assignment by interfaces is introduced. Each interface now has its own address range. This means that there can be several devices with the same device address in the system if they are connected via different interfaces.

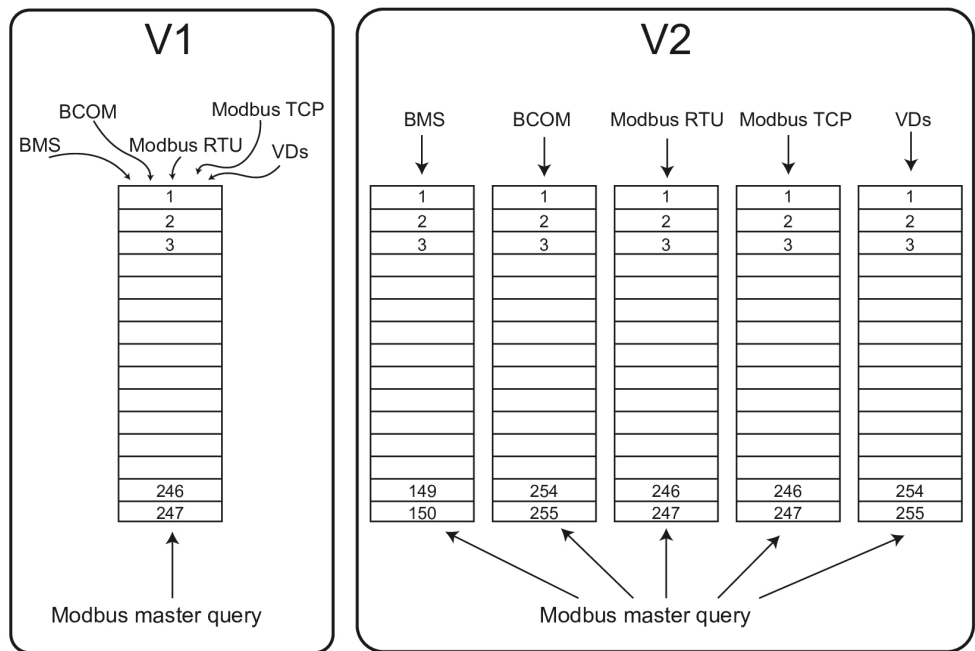


Figure 6-1: Differences between Bender Modbus images V1 and V2

In the **Bender Modbus image V1**, all interfaces share a common address range; in the **Bender Modbus image V2**, each interface has its own address range. The Bender Modbus image V2 guarantees a unique and collision-free access to the device data.

i After updating an existing device to V4.0, the Bender Modbus image is still set to V1. On newly delivered devices, V2 is active by default. The Bender Modbus image is configured in the device menu of the COMTRAXX® device at **Settings > Interface > Modbus**

6.4 Bender Modbus image V1
(one address range for all interfaces)

If the Bender Modbus image is set to V1, the Modbus data are provided as follows:

6.4.1 Querying data with Modbus function code 0x03

The parameters and measured values of all devices in the subsystem can be read using the Modbus function code **0x03** (Read Holding Registers). This is only possible on the subsystem level, not in the entire system. The unit ID refers to the respective device address.

6.4.2 Querying data with Modbus function code 0x04

The system image in the memory of the COMTRAXX® device can be read using the Modbus function code **0x04** (Read Input Registers).

The following information is available for all devices in the system:

- Device name
- Channel states
- Alarm and operating messages

The unit ID refers to the subsystem address.

The volume of the queried data depends on the number of bytes selected in the Modbus client used. Up to 125 words (0x7D) can be read with a single query. An individual word can also be read, for example, to detect the set bit for a saved common alarm.

6.4.3 Writing data with Modbus function code 0x10

The parameters of all devices located in the same subsystem can be written using the Modbus function code **0x10** (Preset Multiple Registers). This is only possible at subsystem level, but not in the whole system. The unit ID refers to the respective device address.



To make it easier to configure device parameters via Modbus TCP, the register addresses for each parameter can be displayed in the device menus. Activate this function at the menu item

 **Tools > Service > Parameter addresses**

6.4.4 Distribution of the memory areas

Memory utilisation	Start address	End of memory area	Size of memory area
Reference values for test purposes	0x0000	0x00FF	0x0100
System image	0x0100	0x95FF	0x9500
Not used	0x96FF	0xFFFF	0x6900



For some Modbus clients an offset of 1 must be added to the register addresses.

Example: process image start address = 0x0101.

The assignment of the memory addresses and the associated memory content for one subsystem is described below. Please refer also to the "BCOM" manual, which provides information about the entire addressable system.

6.4.5 Memory scheme of the system image

Structure of the system image

As illustrated in the table, the Modbus start address for the respective system image is derived from the device address.

256 (0x100) words or 512 bytes are reserved for each device. They contain all information requested and transmitted on the interface.

Modbus start addresses for each device for which a request can be sent (V1)

	Modbus address ranges of the process images in the memory			
Device address	Word			
	HiByte	LoByte		
		00	...	FF
1	0x01	Device 1		
2	0x02	Device 2		
3	0x03	Device 3		
...	...	...		
32	0x20	Device 32		
...	...	...		
255	0xFF	Device 255		

6.4.6 Memory scheme of an individual device

Devices can feature various types of analogue and/or digital channels. Please note the device-specific differences.

After determining the start address, the following unit parameters can be queried:

- Device type
- Timestamp
- Common alarm
- Device error
- Channel information

6.4.7 Example: Determine start address

Channel 2 of the device with address 3 is to be queried. How is the start address determined to send the query for the channel? In our example, the relevant cells in the table are marked in **bold**.

1. For device address 3, the first address part 0x03 (HiByte) is taken from Tab. 7: Modbus start addresses for each device for which a request can be sent (V1).
2. For channel 2, the second address part 0x14 (LoByte) is taken from Tab. 8: Modbus address assignment of the channels in a device (V1).
3. For the number of words to be queried, the number 4 is taken from the same table: (0x14 to 0x17 = 0x04).
4. The start address 0x0314 is formed by HiByte and LoByte

Modbus address assignment of the channels in a device (V1)

Memory image of a device																	
LoByte	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	
0x00	Device type										Timestamp				C	D	R
0x10	Channel 1				Channel 2				Channel 3				Channel 4				

Memory image of a device																
0x20	Channel 5				Channel 6				Channel 7				Channel 8			
0x30	Channel 9				Channel 10				Channel 11				Channel 12			
0x40	Channel 13				Channel 14				Channel 15				Channel 16			
0x50	Channel 17				Channel 18				Channel 19				Channel 20			
0x60	Channel 21				Channel 22				Channel 23				Channel 24			
0x70	Channel 25				Channel 26				Channel 27				Channel 28			
0x80	Channel 29				Channel 30				Channel 31				Channel 32			
0x90	33 34	35 36	37 38	39 40	41 42	43 44	45 46	47 48	49 50	51 52	53 54	55 56	57 58	59 60	61 62	63 64
0xA0	Reserved															
0xB0	Reserved															
0xC0	Reserved															
0xD0	Reserved															
0xE0	Reserved															
0xF0	Reserved															

Hex representation:

horizontal = units

vertical = sixteens

Abbreviations for memory contents:

C = Common alarm

D = Device lost (device failure)

R = Reserved

6.4.8 Data formats

Device type

The device type is set using a bus scan.

Data format device type

Word 0x00	0x01	0x02	0x03	0x04	0x05	0x06	0x07	0x08	0x09
ASCII text, 10 Words/20 Bytes									

Timestamp

The timestamp is set according to a datagram received from a transmitting device.

Data format time stamp

Word 0x0A		0x0B		0x0C		0x0D	
HiByte	LoByte	HiByte	LoByte	HiByte	LoByte	HiByte	LoByte
Year YY		Month MM	Day DD	Hour hh	Minute mm	Second ss	Reserved

C = Common alarm and D = Device lost (device failure)

Data format common alarm and device failure

Word 0x0E	
HiByte	LoByte
C	D
Common alarm, 1 byte: LSB = 0 or 1	Device error, 1 byte: LSB = 0 or 1

The common alarm bit is set as soon as an alarm status from the respective device is detected.
The device error bit is set when the communication with the respective device is no longer possible.

Channels 1...32 with analogue and/or digital values

Every analogue device channel can contain alarm messages, operating messages, measured values, test messages and descriptive text.

Both analogue and digital information can be transmitted.

- A&T = Alarm-Typ and Test-Art (internal/external)
- R&U = Range and unit

For details on the channel description refer to “Channel descriptions for the process image (V1 and V2)”, page 56.

Channels 1...32: Data format analogue/digital values

Word 0x00		0x01		0x02		0x03	
HiByte	LoByte	HiByte	LoByte	HiByte	LoByte	HiByte	LoByte
Floating point value (Float)				A&T	R&U	Channel description	

Float = Floating point value of the channels

Channels 1...32: Data format floating point values

Word	0x00																0x10															
Byte	HiByte								LoByte								HiByte								LoByte							
Bit	31	30						24	23							16	15							8	7							0
	S	E	E	E	E	E	E	E	E	M	M	M	M	M	M	M	M	M	M	M	M	M	M	M	M	M	M	M	M	M	M	

Representation of the bit order for processing analogue measured values according to IEEE 754

S = Sign

E = Exponent

M = Mantissa

A&T = Alarm type and test type (internal/external)

The alarm type is coded by the bits 0...2.

The bits 3 and 4 are reserved and always have the value 0.

Bit 5 usually has the value 0 and represents the digital value of the status (this column is only relevant for the SMI472).

Bit 6 or 7 are usually set when an internal or external test has been completed. Other values are reserved.

The complete byte is calculated from the sum of the alarm type and the test type.

Channels 1...32: Data format A&T

Bit	7	6	5	4	3	2	1	0	Description
	a)	b)	c)	d)	d)	e)	f)		
Alarm type	-	-	-	-	-	0	0	0	No alarm
	-	-	-	-	-	0	0	1	Prewarning
	0	0	-	-	-	0	1	0	Device error
	-	-	-	-	-	0	1	1	Reserved
	-	-	-	-	-	1	0	0	Alarm (yellow LED), e.g. insulation fault
	-	-	-	-	-	1	0	1	Alarm (red LED)
	-	-	-	-	-	1	1	0	Reserved
	-	-	-	-	-	1	1	1	Reserved
Test	0	0	-	-	-	-	-	-	No test
	0	1	-	-	-	-	-	-	Internal test
	1	0	-	-	-	-	-	-	External test

a) = External test

b) = Internal test

c) = Status

d) = Reserved

e) = Alarm

f) = Error

R&U = Range and Unit

The unit is coded in the bits 0...4.

Bit 5 is reserved.

The bits 6 and 7 describe the range of validity of a value.

The complete byte is calculated from the sum of the unit and the range of validity.

Channels 1...32: Data format R&U

Bit	7	5	5	4	3	2	1	0	Description
Unit	-	-	-	0	0	0	0	0	Invalid(init)
	-	-	-	0	0	0	0	1	No unit
	-	-	-	0	0	0	1	0	Ω
	-	-	-	0	0	0	1	1	A
	-	-	-	0	0	1	0	0	V
	-	-	-	0	0	1	0	1	%
	-	-	-	0	0	1	1	0	Hz
	-	-	-	0	0	1	1	1	Baud
	-	-	-	0	1	0	0	0	F
	-	-	-	0	1	0	0	1	H
	-	-	-	0	1	0	1	0	°C
	-	-	-	0	1	0	1	1	°F
	-	-	-	0	1	1	0	0	Second
	-	-	-	0	1	1	0	1	Minute
	-	-	-	0	1	1	1	0	Hour
	-	-	-	0	1	1	1	1	Day
	-	-	-	1	0	0	0	0	Month
	-	-	-	1	...	...	...	...	Reserved
	-	-	-	1	1	1	1	0	CODE
	-	-	-	1	1	1	1	1	Reserved
	-	-	1	...	...	...	...	...	
	-	-	1	1	1	1	1	1	
Range of validity	0	0	-	-	-	-	-	-	Actual value
	0	1	-	-	-	-	-	-	The actual value is lower
	1	0	-	-	-	-	-	-	The actual value is higher
	1	1	-	-	-	-	-	-	Invalid value

i If the unit byte (0...4) refers to CODE, the recorded value or status will result in a text message.

The content of this text message is listed in the table "Channel descriptions for the process image (V1 and V2)", page 56. The floating point value contains an internal CODE but no valid measured value.

Channel description

A code with the associated descriptive text is available for each channel. For a complete list of the available codes or texts refer to "Channel descriptions for the process image (V1 and V2)", page 56.

Channels 33...64

The channels 33...64 only provide digital information. The information is coded as alarm or message type as well as test type (internal/external). The coding is similar to the A&T data format for channels 1...32 except for the additional bit 4, which is used for coding device errors, e.g. connection faults or internal device errors.

Channels 33...64: Data format A&T

Bit	7	5	5	4	3	2	1	0	Description
	a)	b)	c)	d)	e)	f)	g)		
Alarm-Typ	-	-	-	-	-	0	0	0	No alarm
	-	-	-	-	-	0	0	1	Prewarning
	0	0	-	-	-	0	1	0	Device error
	-	-	-	-	-	0	1	1	Reserved
	-	-	-	-	-	1	0	0	Alarm (yellow LED), e.g. insulation fault
	-	-	-	-	-	1	0	1	Alarm (red LED)
	-	-	-	-	-	1	1	0	Reserved
	-	-	-	-	-	1	1	1	Reserved
Test	0	0	-	-	-	-	-	-	No test
	0	1	-	-	-	-	-	-	Internal test
	1	0	-	-	-	-	-	-	External test

a) = External test

b) = Internal test

c) = Status

d) = Device error

e) = Reserved

f) = Alarm

g) = Error

6.4.9 Modbus example for reading data (V1)

Example: Reading out from ATICS channel 1 (voltage line 1)

Reading out from ATICS channel 1 (voltage line 1) The COMTRAXX® device has address 1 in subsystem 1. ATICS channel 1 of internal address 3 is to be read out. The content is the voltage of line 1 as floating point value.

Modbus request for "reading data (V1)"

00 01 00 00 00 06 01 04 03 10 00 02

00 01 Transaction ID (is generated automatically)

00 00 Protocol ID

00 06 Length

01	Unit ID (subsystem 1)
04	Modbus Function Code 0x 04 (read input registers)
03 10	Start register (register address at which the value appears in the memory image: 784 = 0x 03 10)
00 02	Length of the data (words)

Modbus responsefor "reading data (V1)"

00 01 00 00 00 05 01 04 04 01 00 43 63 00 04	
00 01	Transaction ID (is generated automatically)
00 00	Protocol ID
00 05	Length
01	Unit ID (device address of the COMTRAXX® device)
04	Modbus Function Code 0x 04 (read input registers)
04	Length of the data (bytes)
01 00 43 63	Data floating point value (0x 43 63 01 00 (words swapped) = 227.0039)
00 04	Alarm and test type (00 = no alarm), range and unit (04 = volts)

6.4.10 Reference data records of the process image

To make it easier to check the configuration and the Modbus TCP data access to devices, the COMTRAXX® device provides a reference data record at the **virtual** address 0

 *No real device can have address 0! Address 0 only serves to simulate data access.*

Special features of the Modbus communication are the byte offset and the word and byte order in the memory (Big Endian, MSB). At the end of this chapter, a few examples of correct configuration are given, which might be helpful.

6.4.11 Address assignment of the reference data record

As shown in the following table, the Modbus start address for access to the reference data record is derived from device address 0.

Start addresses for the reference data record query

Virtual device address	Word				
	HiByte	LoByte			
		00	0E	10	14
0	0x00	Device type	Common alarm	Channel 1	Channel 2

The start addresses provide the following reference values

- 0x0000: TEST (device type)
- 0x000E: 1 (common alarm, LSB of the HiByte is set)
- 0x0010: 230 V undervoltage (reference value on channel 1)
- 0x0014: 12.34 A overcurrent (reference value on channel 2)

6.4.12 Reference value on channel 1

The following reference value is stored in this channel: 230.0 V undervoltage

Stored reference data (channel 1)

Word 0x10		0x11		0x12		0x13	
HiByte	LoByte	HiByte	LoByte	HiByte	LoByte	HiByte	LoByte
0x43	0x66	0x00	0x00	0x00	0x04	0x00	0x4D
Floating point value (Float)				A&T	R&U	Description	
230.0				No/No	Volt	Undervoltage	

6.4.13 Reference value on channel 2

The following reference value is stored in this channel: 12.34 A

Stored reference data (channel 2)

Word 0x14		0x15		0x16		0x17	
HiByte	LoByte	HiByte	LoByte	HiByte	LoByte	HiByte	LoByte
0x41	0x45	0x70	0xA4	0x00	0x03	0x00	0x4A
Floating point value(Float)				A&T	R&U	Description	
12.34				No/No	Ampere	Overcurrent	

6.4.14 Explanation of how to access floating point values

The test value 12.34 can be read out via Modbus TCP using the Modbus function code **0x04** at the address 0x0014. The test value has a size of 2 words.

Proceed as follows:

1. Determine the correct byte offset

Interpreting both words as unsigned integer values should result in the following values: Word 1 with address 0x14: unsigned integer value => 16709 (0x4145) Word 2 with address 0x15: unsigned integer value => 28836 (0x70A4)

2. Determine the correct byte or word swap

There are four different combinations of swapping. The only correct value is 12.34. All swapping combinations are represented in the following table:

Hex value sequence	Word 1		Word 2		Floating point value
	Byte 1	Byte 2	Byte 3	Byte 4	
CORRECT	A 41	B 45	C 70	D A4	12.34
Word swapping	C 70	D A4	A 41	B 45	4.066E+29

Hex value sequence	Word 1		Word 2		Floating point value
	Byte 1	Byte 2	Byte 3	Byte 4	
Byte swapping	B 45	A 41	D A4	C 70	3098.27
Word and byte swapping	D A4	C 70	B 45	A 41	-5.21E-17

6.5 Bender Modbus image V2

(one address range for each interface)

If the Bender Modbus image is set to V2, the Modbus data are provided as follows.

6.5.1 Function codes (V2)

Function code 0x03 (Read Holding Registers):

Querying data from the Modbus device assignment table

- **Reading** the parameters and measured values of all devices in the system
- Modbus device assignment must be performed before use, because the unit ID in the Modbus request refers to the respective unit ID assigned in the Modbus device assignment.
- The device assignment determines which devices are accessible via **0x03**.
- 255 addresses are available, which can be configured freely.
- The device assignment takes place in the CONTRAXX® device at

 **Device management > Device assignment > Modbus.**

Function code 0x10 (Write Multiple Registers):

Writing data

Writing the parameters of all devices in the subsystem

For the Modbus request, the unit ID refers to the interface via which the corresponding device is integrated.

 *To set parameters for devices via Modbus TCP, a device assignment must first be made in order to obtain unique unit IDs:*

In order to perform a parameter setting for devices via Modbus TCP, a device mapping must first be carried out in order to obtain unique Unit IDs:

 **Tools > Device management > Device assignment > Modbus.**

Note that there may be a time delay of up to 3 minutes in BMS bus operations before changes become visible.

 *To make it easier to configure device parameters via Modbus TCP, the register addresses for each parameter can be displayed in the device menus. Activate this function at the menu item*

 **Tools > Service > Parameter addresses**

Function code 0x04 (Read Input Registers):

Querying data from the system image

- **Reading** the system image from the COMTRAXX® device memory.
- Querying device names, channel states, alarm and operating messages from all devices connected via the COMTRAXX® device.
- Here, the unit ID refers to the interface via which the corresponding device is connected.
- The volume of the queried data depends on the number of bytes selected in the Modbus client used.
- Up to 125 words (0x7D) can be read with a single query.

6.5.2 Distribution of the memory areas (V2)

Unit-ID	Interface	Maximum No. of devices	Measuring points per device	Register per device	Device/Register per unit ID	Device/Register last unit ID	Start address	End address
1	COMTRAXX® device information	1	550	8880	1/8880	-	0	8879
10	Internal BMS	150	12	272	150 / 40800	-	0	40799
20... 28	Modbus RTU	247	128	2128	30 / 63840	7 / 14896	0 (per unit ID)	14895 (Unit- ID 28)
40... 48	Modbus TCP	247	128	2128	30 / 63840	7 / 14896	0 (per unit ID)	14895 (Unit- ID 48)
60... 68	BCOM	255	128	2128	30 / 63840	15 / 31920	0 (per unit ID)	31919 (Unit- ID 68)
90... 91	Virtual devices	255	16	336	195 / 65520	60 / 20160	0 (per unit ID)	20159 (Unit- ID 91)
95	I ² C	127	16	336	127 / 42672	-	0	42671
101... 199 ¹⁾	²⁾	150 per unit ID	12	272	150 / 40800	-	0 (per unit ID)	40799 (Unit- ID 199)

¹⁾ Only for devices with the corresponding interface; otherwise: reserved

²⁾ External BMS: Here, the unit ID represents an external BMS address .
BMS_{Se} Addr. 10 = unit ID 110



*For some Modbus clients an offset of 1 must be added to the register addresses.
Example: process image start address = 0x0101.*

6.5.3 Memory scheme of the system image (V2)

Structure of the system image

As illustrated in the table, the Modbus start address for the respective system image is derived from the device address. It contains all information requested and transmitted on the interface

Example: Internal BMS

Unit ID	Device address	Modbus address ranges of the data in the memory	
		Start register	End register
10	1	0 (272 x 0)	271 (272 x 1 - 1)
10	2	272 (272 x 1)	543 (272 x 2 - 1)
10	3	544 (272 x 2)	815 (272 x 3 - 1)
...			
10	30	7888 (272 x 29)	8159 (272 x 30 - 1)
10	31	8160 (272 x 30)	8431 (272 x 31 - 1)
...			
10	150	40528 (272 x 149)	40799 (272 x 150 - 1)

Example: Modbus TCP

Unit ID	Device address	Modbus address ranges of the data in the memory	
		Start register	End register
40	1	0 (2128 x 0)	2127 (2128 x 1 - 1)
40	2	2128 (2128 x 1)	4255 (2128 x 2 - 1)
40	3	4256 (2128 x 2)	6383 (2128 x 3 - 1)
...			
40	30	61712 (2128 x 29)	63.839 (2128 x 30 -1)
40	31	0 (2128 x 0)	2127 (2128 x 1 - 1)
...			
40	247	12768 (2128 x6)	14.895 (2128 x 7 - 1)

6.5.4 Memory scheme of a device (V2)

Example: Memory scheme V2: Device internal BMS

Each device is managed via an individual device image in the memory. Its first block provides the device information. Afterwards, the individual measured value/channel information is displayed. The size of the block depends on how many measured values a device provides.

Device (V2)

Default values in case no values are available for the requested register:

- UINT16: 65.535 (all bits are set)
- UINT32: 4.294.967.295 (all bits are set)
- String: empty string (value 0)
- Float: NaN (all bits are set)

Offset	Hex	Type	Length in Words	Extended description
0	0	String	10	Device name
10	A	String	10	Serial number of the device
20	14	UINT32	2	Last contact (time stamp in seconds since 01.01.1970)
22	16	UINT16	1	Device status 2 = Inactive (Device is not active. However, devices connected to this device are monitored for failure) 3 = Active (Device is active) 4 = Lost (Device is not active but is monitored for failure)
23	17	UINT16	1	Sum of all messages (alarm, warning, prewarning, device error)
24	18	UINT16	1	Number of alarms
25	19	UINT16	1	Number of warnings
26	1A	UINT16	1	Number of prewarnings
27	1B	UINT16	1	Number of device errors
28	1C	UINT16	52	Individual device range, the content depends on the respective device
			Sum = 80	

Example: Memory scheme V2: Device internal BMS

Description	Words
Device information	80
Measured values	192 (12 channels x 16 words per channel))
Total	272

Measured value (V2)

Offset	Hex	Type	Length in words	Extended description
0	0	UINT32	2	Time stamp in seconds since 01.01.1970
2	2	Float	2	Measured value (NaN if not valid)
4	4	Float	2	Response value (not available for every device; if not available, NaN)

Offset	Hex	Type	Length in words	Extended description
6	6	Float	2	Response value for prewarning (not available for every device; if not available, NAN)
8	8	UINT16	1	Alarm type 0 = None 1 = Prewarning 2 = Fault 4 = Warning 5 = Alarm
9	9	UINT16	1	Unit 1 = None 2 = Ohm 3 = Ampere 4 = Volt 5 = Percent 6 = Hertz 7 = Baud 8 = Farad 9 = Henry 10 = °Celsius 11 = °Fahrenheit 12 = Second 13 = Minute 14 = Hour 15 = Day 16 = Month 17 = Watt 18 = var 19 = VA 20 = Wh 21 = varh 22 = VAh 23 = Degree 24 = HertzPerSecond 25 = NonewithConvert 26 = Bar 30 = Textcode
10	A	UINT16	1	Range of validity 0 = Actual value 1 = Actual value is lower < 2 = Actual value is higher > 3 = Invalid value
11	B	UINT16	1	Test 0 = None 1 = Internal 2 = External
12	C	UINT16	1	Description

Offset	Hex	Type	Length in words	Extended description
13	D	UINT16	1	Reserved (0xFFFF)
14	E	UINT16	1	Compressed channel state Bit coded 1 = Message present 2 = Prewarning 4 = Fault/Alarm/Warning 8 = Internal test 16 = External test
15	F		1	Reserved
			Sum = 16	

6.5.5 Modbus example for reading data (V2)

Example: Reading out from ATICS channel 1 (voltage line 1)

The COMTRAXX® device has address 1 in subsystem 1.

Channel 1 of an ATICS is to be read out at the internal BMS with address 3. The content is the voltage of line 1 as floating point value.

Modbus request for "reading data (V2)"

00 01 00 00 00 06 0A 04 02 72 00 02

00 01 Transaction ID (is generated automatically)
00 00 Protocol ID
00 06 Length
0A Unit-ID (internal BMS)
04 Modbus Function Code 0x 04 (read input registers)
02 72 Start register (272 [words per device] * 2 [address 3] + 82 [Start register measured value channel 1])
00 02 Length of the data (words)

Modbus response for "reading data (V2)"

00 01 00 00 00 05 0A 04 04 01 00 43 63 00 04

00 01 Transaction ID (is generated automatically)
00 00 Protocol ID
00 05 Length
0A Unit-ID (internal BMS)
04 Modbus Function Code 0x 04 (read input registers)
04 Length of the data (bytes)
01 00 43 63 Data floating point value (0x 43 63 01 00 (words swapped) = 227.0039)
00 04 Alarm and test type (00 = no alarm), range and unit (04 = volts)

6.5.6 Reference data records of the system image (V2)

To check the configuration and the Modbus TCP data access, internal registers of the COMTRAXX® device can be retrieved with function code **0x04**.

Address assignment of the reference data record

Information on the COMTRAXX® device can be retrieved in the following registers. This can be used to check the configuration and the Modbus TCP data access to the device.

Modbus address ranges of the data in the memory						
Content	Unit-ID	Device address	Start register	End register	Type	Length
Device name	1	1	0x00 00	0x00 09	String	10 words
Serial number	1	1	0x00 0A	0x00 13	String	10 words

6.6 Channel descriptions for the process image (V1 and V2)

Channel descriptions for the process image

Value	Measured value description Alarm message Operating message	Description
1 (0x01)	Insulation fault	
2 (0x02)	Overload	
3 (0x03)	Overtemperature	
4 (0x04)	Failure line 1	
5 (0x05)	Failure line 2	
6 (0x06)	Insul. OT light	Insulation fault operating theatre light
7 (0x07)		
8 (0x08)	Distribution board failure	
9 (0x09)	Failure oxygen	
10 (0x0A)	Failure vacuum	
11 (0x0B)	Anaesthetic gas	
12 (0x0C)	Compressed air 5 bar	
13 (0x0D)	Compressed air 10 bar	
14 (0x0E)	Failure nitrogen	
15 (0x0F)	Failure CO2	
16 (0x10)	Insulation UPS	Insulation fault UPS
17 (0x11)	Overload UPS	
18 (0x12)	Converter UPS	
19 (0x13)	UPS fault	
20 (0x14)	UPS emergency peration	
21 (0x15)	UPS test run	

Value	Measured value description Alarm message Operating message	Description
22 (0x16)	Failure air conditioning	
23 (0x17)	Batt.op. OP-L	Battery-operated operating theatre light
24 (0x18)	Batt.op. OP-S	Battery-operated Sat operating theatre light
25 (0x19)	Fail.norm.supply	Line normal power supply
26 (0x1A)	Fail.safet.supply	Line safety power supply
27 (0x1B)	Failure UPS	Line additional safety power supply
28 (0x1C)	Ins.safety supply	
29 (0x1D)	Fail.N conductor	
30 (0x1E)	Short dist. panel	Distribution panel short circuit
31 (0x1F)	Reserved	
32 (0x20)		
33 (0x21)		
34 (0x22)		
35 (0x23)	Standby function	(Measuring function switched off (standby))
36 (0x24)		
37 (0x25)		
38 (0x26)	Batt.op. UPS	Battery operation, special safety power supply
39 (0x27)	Phase sequ. left	
40 (0x28)	Failure line BPS	Battery-supported safety power supply
41 (0x29)	Reserved	
...		
66 (0x42)		
67 (0x43)	Function test until:	Date
68 (0x44)	Service until:	Date
69 (0x45)	Ins.fault locat.	Insulation fault location
70 (0x46)	peak	Fault EDS system
71 (0x47)	Insulation fault	Insulation resistance in W
72 (0x48)	Current	Measured value in A
73 (0x49)	Undercurrent	
74 (0x4A)	Overcurrent	

Value	Measured value description Alarm message Operating message	Description
75 (0x4B)	Residual current	Measured value in A
76 (0x4C)	Voltage	Measured value in V
77 (0x4D)	Undervoltage	
78 (0x4E)	Overvoltage	
79 (0x4F)	Frequency	Measured value in Hz
80 (0x50)	Reserved	
81 (0x51)	Unbalance	
82 (0x52)	Capacitance	Measured value in F
83 (0x53)	Temperature	Measured value in °C
84 (0x54)	Overload	Measured value in %
85 (0x55)	Digital input	State 0 or 1
86 (0x56)	Insulation fault	Impedance
87 (0x57)	Insulation fault	Alarm from an insulation fault locator
88 (0x58)	Load	Measured value in %
89 (0x59)	Total Hazard Current	THC
90 (0x5A)	Inductance	Measured value in H
...	Reserved	
97 (0x61)	Service code	Information about service intervals
...	Reserved	
101 (0x65)	Mains power connection	
102 (0x66)	Earth connection	
103 (0x67)	Short-circuit transformer	CT short circuit
104 (0x68)	No CT connected	
105 (0x69)	Short temp.sensor	Temperature sensor short circuit
106 (0x6A)	Temp.sensor open.	Connection temperature sensor
107 (0x6B)	K1	Fault contactor K1
108 (0x6C)	K2	Fault contactor K2
109 (0x6D)	Reserved	
110 (0x6E)		
111 (0x6F)	No address:	Failure BMS device
112 (0x70)	Reserved	

Value	Measured value description Alarm message Operating message	Description
113 (0x71)	Failure K1/Q1	Failure contactor K1/Q1
114 (0x72)	Failure K2/Q2	Failure contactor K2/Q2
115 (0x73)	Device error	Fault ISOMETER
116 (0x74)	Manual mode K1/2	Manual mode
117 (0x75)	Open circuit K1 on	Line to K1 interrupted on
118 (0x76)	Open circuit K1 off	Line to K1 interrupted off
119 (0x77)	Open circuit K2 on	Line to K2 interrupted on
120 (0x78)	Open circuit K2 off	Line to K2 interrupted off
121 (0x79)	K/Q1 on	Fault
122 (0x7A)	K/Q1 off	Fault
123 (0x7B)	K/Q2 on	Fault
124 (0x7C)	K/Q2 off	Fault
125 (0x7D)	FailureK3	
126 (0x7E)	Q1	Fault
127 (0x7F)	Q2	Fault
128 (0x80)	No master	
129 (0x81)	Device error	
130 (0x82)	Reserved	
131 (0x83)	Fault RS485	
132 (0x84)	Reserved	
133 (0x85)		
134 (0x86)		
135 (0x87)		
136 (0x88)		
137 (0x89)	Short circuit Q1	
138 (0x8A)	Short circuit Q2	
139 (0x8B)	CV460	CV460 fault
140 (0x8C)	RK4xx	Fault RK4xx
141 (0x8D)	Address collision	BMS address has been assigned several times
142 (0x8E)	Invalid address	
143 (0x8F)	Several masters	

Value	Measured value description Alarm message Operating message	Description
144 (0x90)	No menu access	
145 (0x91)	Own address	
...	Reserved	
201 (0xC9)	Line 1 normal op	
202 (0xCA)	Line 2 normal op	
203 (0xCB)	Switch. el. 1 on	
204 (0xCC)	Switch. el. 2 on	
205 (0xCD)	Reserved	
206 (0xCE)	Auto mode	
207 (0xCF)	Manual mode	
208 (0xD0)	Reserved	
209 (0xD1)		
210 (0xD2)	Line AV on	
211 (0xD3)	Line SV on	
212 (0xD4)	Line UPS on	
213 (0xD5)	Channel disabled	
214 (0xD6)	Switch-back lock	Switch-back lock enabled
215 (0xD7)	Phase sequ. right	
216 (0xD8)	Switch. el. pos.0	
217 (0xD9)	Line BPS on	
218 (0xDA)	On	SMO48x: Alarm, relay
219 (0xDB)	Relay off	
220 (0xDC)	Automatic test	
221 (0xDD)	Initial measurement	

Value	Measured value description Alarm message Operating message	Description
256 (0x100)	DC offset voltage	
257 (0x101)	Overtemperature coupling	
258 (0x102)	Overtemp. PGH	
259 (0x103)	ISONet active	

Value	Measured value description Alarm message Operating message	Description
260 (0x104)	Maximum count reached	
261 (0x105)	THD	
262 (0x106)	Insulation fault at L1	
263 (0x107)	Insulation fault at L2	
264 (0x108)	Insulation fault at L3	
265 (0x109)	Res. Hazard Current	
266 (0x10A)	No. active EDS channels	
267 (0x10B)	No. detected ins. faults	
268 (0x10C)	No. resid. current faults	
269 (0x10D)	Fault location	
270 (0x10E)	Calibration	
271 (0x10F)	U NGR(rms) limit exceeded	
272 (0x110)	I NGR(rms) limit exceeded	
273 (0x111)	Fault voltage U NGR (fundamental)	
	U NGR(fund) limit exceeded	
274 (0x112)	I NGR(fund) limit exceeded	
275 (0x113)	Line 3 operational	
276 (0x114)	Failure line 3	
277 (0x115)	R NGR below threshold	
278 (0x116)	R NGR above threshold	
279 (0x117)	Earth fault L1	
280 (0x118)	Earth fault L2	
281 (0x119)	Earth fault L3	
282 (0x11A)	Fault phase L1	
283 (0x11B)	Fault phase L2	
284 (0x11C)	Fault phase L3	
285 (0x11D)	Locating current	
286 (0x11E)	Switch. elem. 3 on	
287 (0x11F)	Q3	
288 (0x120)	Switch. elem. 1 off	
289 (0x121)	Switch. elem. 2 off	

Value	Measured value description Alarm message Operating message	Description
290 (0x122)	Switch. elem. 3 off	
291 (0x123)	Wire break K3/Q3 on	
292 (0x124)	Wire break K3/Q3 off	
293 (0x125)	Fault K/Q3 on	
294 (0x126)	Fault K/Q3 off	
295 (0x127)	Connection monitoring auxiliary voltage switch	
296 (0x128)	Bypass operation	
297 (0x129)	Tripped	
298 (0x12A)	Latched fault after device restart	
299 (0x12B)	U NGR(harm) limit exceeded	
300 (0x12C)	I NGR(harm) limit exceeded	
301 (0x12D)	Restart	
302 (0x12E)	Insulation resistance from DC shift voltage	
303 (0x12F)	System error	
304 (0x130)		
305 (0x131)	R NGR	
306 (0x132)	R NGR relative	
307 (0x133)	I NGR RMS	
308 (0x134)	I NGR RMS relative	
309 (0x135)	I NGR fundamental	
310 (0x136)	I NGR fundamental relative	
311 (0x137)	I NGR harmonics	
312 (0x138)	I NGR harmonics relative	
313 (0x139)	U NGR RMS	
314 (0x13A)	U NGR RMS relative	
315 (0x13B)	U NGR fundamental	
316 (0x13C)	U NGR fundamental relative	
317 (0x13D)	U NGR harmonics	
318 (0x13E)	U NGR harmonics relative	
319 (0x13F)	U(1-2)	

Value	Measured value description Alarm message Operating message	Description
320 (0x140)	U(2-3)	
321 (0x141)	U(3-1)	
322 (0x142)	U(1-E)	
323 (0x143)	U(2-E)	
324 (0x144)	U(3-E)	
325 (0x145)	Method	
326 (0x146)	R sense	
327 (0x147)	Symmetrical alarm	
328 (0x148)	OK	
329 (0x149)	TEST	
330 (0x14A)	Enable synchronous switchover	
331 (0x14B)	Service profile	
332 (0x14C)	Switch-on time Q1	
333 (0x14D)	Switch-off time Q1	
334 (0x14E)	Switch-on time Q2	
335 (0x14F)	Switch-off time Q2	
336 (0x150)	Switch-on time Q3	
337 (0x151)	Switch-off time Q3	
338 (0x152)	Prewarning	
339 (0x153)		
340 (0x154)		
341 (0x155)	Peak demand	
342 (0x156)	Quadrant	
343 (0x157)		
344 (0x158)	TDD	
345 (0x159)	TODD	
346 (0x15A)	TEDD	
347 (0x15B)	Demand	
348 (0x15C)	Zero sequence	
349 (0x15D)	Positive sequence	
350 (0x15E)	Negative sequence	

Value	Measured value description Alarm message Operating message	Description
351 (0x15F)	Digital output	
352 (0x160)	Deviation	
353 (0x161)	Flicker Pst	
354 (0x162)	Flicker Plt	
355 (0x163)	Overdeviation	
356 (0x164)	Underdeviation	
357 (0x165)	Crest factor	
358 (0x166)	All harmonics	
359 (0x167)	Fundamental	
360 (0x168)	TOHD	
361 (0x169)	TEHD	
362 (0x16A)	TIHD	
363 (0x16B)	TOIHD	
364 (0x16C)	TEIHD	
365 (0x16D)	IHD	
366 (0x16E)	Voltage dips	
367 (0x16F)	Voltage swells	
368 (0x170)	Voltage interruptions	
369 (0x171)	Transients	
370 (0x172)	Rapid voltage changes	
371(0x173)	All PQ events	
372 (0x174)	Demand forecast	
373 (0x175)	Q1 not ready	
374 (0x176)	Q2 not ready	
375 (0x177)	Q3 not ready	
376 (0x178)	Measured value counter	
377 (0x179)	Alarm messages	
378 (0x17A)	DC shift value in percent	
379 (0x17B)	Demand import	
380 (0x17C)	Demand export	
381 (0x17D)	Max. this month	

Value	Measured value description Alarm message Operating message	Description
382 (0x17E)	Min. this month	
383 (0x17F)	Max. last month	
384 (0x180)	Min. last month	
385 (0x181)	Generator switch-off delay	
386 (0x182)	ISOSync active	
387 (0x183)	Analogue input	
388 (0x184)	Analogue output	
389 (0x185)	brighter	
390 (0x186)	darker	
391 (0x187)	nominal value	
392 (0x188)	actual value	
393 (0x189)		
394 (0x18A)		
395 (0x18B)	Overload on current input	
396 (0x18C)	DC immunity	
397 (0x18D)	Field calibration failed	
398 (0x18E)	Field calibration could not be started	
399 (0x18F)	Autom. restart failed!	
400 (0x190)	Failure alarm indicator panel	
401 (0x191)	up	
402 (0x192)	down	
403 (0x193)	The EDSsync configuration is not consistent!	
404 (0x194)	BCOM connection interrupted!	
405 (0x195)	The EDSsync configuration was not found!	
406 (0x196)	Distribution of EDSsync configuration has failed!	
407 (0x197)	The EDSsync configuration is faulty!	
408 (0x198)	EDSsync is active	
409 (0x199)	EDSsync is deactivated	
410 (0x19A)	EDSsync device cannot be reached!	
411 (0x19B)	ISOnet priority	

Value	Measured value description Alarm message Operating message	Description
412 (0x19C)	Insulation measurement	
413 (0x19D)	The ISOloop configuration is not consistent!	
414 (0x19E)	The ISOloop configuration has not been found!	
415 (0x19F)	Distribution of ISOloop configuration failed!	
416 (0x1A0)	The ISOloop configuration is faulty!	
417 (0x1A1)	ISOloop active	
418 (0x1A2)	ISOloop is deactivated	
419 (0x1A3)	ISOloop device not reachable!	
420 (0x1A4)	RMS residual current	
421 (0x1A5)	changeover period	
422 (0x1A6)	EDSsync: No active ISOMETER!	
423 (0x1A7)	Set up group	
424 (0x1A8)	Not available	
425 (0x1A9)	Wrong configuration	
426 (0x1AA)	Estimated insulation value	
427 (0x1AB)	Approximate insulation value	
428 (0x1AC)	Too many EDSsync participants!	
429 (0x1AD)	Insulation fault R(an) 1	
430 (0x1AE)	Insulation fault R(an) 2	

To convert parameter data, data type descriptions are required. Text representation is not necessary in this case.

Data type descriptions

Value	Description of parameters
1023 (0x3FF)	Parameter/measured value invalid. The menu item for this parameter is not displayed
1022 (0x3FE)	No measured value/no message
1021 (0x3FD)	Measured value/parameter inactive
1020 (0x3FC)	Measured value/parameter only temporarily inactive (e.g. during the transfer of a new parameter). Display in the menu "...".
1019 (0x3FB)	Parameter/measured value (value) unit not displayed
1018 (0x3FA)	Parameter (code selection menu) unit not displayed

Value	Description of parameters
1017 (0x3F9)	String max. 18 characters (e.g. device type, device variant, ...)
1016 (0x3F8)	Reserved
1015 (0x3F7)	Time
1014 (0x3F6)	Date day
1013 (0x3F5)	Date month
1012 (0x3F4)	Date year
1011 (0x3F3)	Register address (unit not displayed)
1010 (0x3F2)	Time
1009 (0x3F1)	Multiplication [°]
1008 (0x3F0)	Division [/]
1007 (0x3EF)	Baud rate

6.7 Modbus control commands

Commands can be sent to BMS devices by an external application (e.g. a visualisation software).

This functionality can be activated or deactivated via the web user interface.

Command structure

Write				Read
Word 0xFC00	0xFC01	0xFC02	0xFC03	0xFC04
Subsystem-Adresse	BMS bus address	BMS channel	Command	Status

6.7.1 Writing to registers

- Use function code **0x10** (Preset Multiple Registers) for writing.
- If no BMS channel number is required, enter the value "0" (zero) in the corresponding register.
- Always set all four registers (word 0xFC00...0xFC03) at the same time. This statement also applies if individual registers remain unchanged.
- If no other subsystem is available, enter value "1" in this register.
- If a BMS channel number is not required, enter value "0" (zero) in this register

 *Control commands can also be generated in the menu **Service > Modbus > Modbus control commands**.*

6.7.2 Reading registers

Use function code **0x03** "Read Input Registers" to read.

Possible response in "Status" register

0	Busy	Processing command.
1	Error	An error has occurred.
2	Ready	Command has been processed successfully.

6.7.3 Control commands for the internal BMS bus

BMS bus control commands

Register Int	Register Channel	Register Command	Menu text / Function
1...150	0	1	Test Isometer
1...150	0	2	Test change over unit (PRC487) /
1...150	0	3	Test change over unit (ATICS) / Start automatischer Test Umschaltung 1->2 Ende nach der Zeit T(Test) Test changeover unit (ATICS) / Start automatic test changeover 1->2 / End after time T(test)
1...150	0	4	Start test generator without change over (ATICS) /
1...150	0	5	Change over to line 1 (ATICS)
1...150	0	6	Change over to line 2 (ATICS)
0	0	7	Reset alarm (all devices) / RESET Alarm (Broadcast)
0	0	8	Clear EDS insulation alarm (EDS) / RESET Alarm EDS (Broadcast)
1...150	0	9	Mute buzzer (MK, TM, LIM) / Mute buzzer [for alarm address] (BC)
1...150	1...12	10	Switch channel on (SMO481; PRC487): channel 1: Change over to line 1; channel 2: Change over to line 2 / Switch on relay/switch
1...150	1...12	11	Switch channel off (SMO481) / Switch off relay/switch
1...150	1...12	14	Test (EDS, RCMS)

6.7.4 Modbus example for control commands

Example: Changeover of ATICS to line 1

The COMTRAXX® device has the address 1 in subsystem 1. An ATICS of internal address 3 is to be changed over to line 1.

Modbus control command

00 02 00 00 00 0F 01 10 FC 00 00 04 08 00 01 00 03 00 00 00 05

00 02	Transaction ID (is generated automatically)
00 00	Protocol ID
00 0F	Length
00	Always 00
10	Modbus function code 0x10 (write multiple registers)
FC 00	Start register
00 04	Number of registers
08	Length of the data
00 01	Always 00 01
00 03	Value 2 (internal address: ATICS address 3)
00 00	Value 3 (channel address: always has to be 0)
00 05	Value 4 (command)

Modbus response

00 02 00 00 00 06 01 10 FC 00 00 04

00 02	Transaction ID (is generated automatically)
00 00	Protocol ID
00 06	Length
00	Always 00
10	Modbus function code 0x10 (write multiple registers)
FC 00	Start register
00 04	Number of registers

7 Modbus RTU Slave

i Addresses 1...5 of the internal BMS bus are provided via Modbus RTU with the basic device. Function module "Interfaces" is required to use the entire address range.

i Support tools that provide comprehensive information about Modbus can be found in the web user interface at  **Tools > Service > Modbus RTU**

- Generate control commands for BMS
- Display information on all available Modbus registers.
- Generate Modbus documentation of all available Modbus registers of the connected devices.

These support tools are only active when the Modbus RTU interface is operated as a slave.

The Modbus RTU interface can be operated in master or slave mode.

- In **master mode**, device information is integrated into the COMTRAXX® system.
- In **slave mode**, the measured values and alarm states of the connected BMS devices are provided.

The detailed Modbus register data and all other information is presented in the support tools listed above.

Configuration of the Modbus-RTU interface

The configuration of the Modbus RTU interface takes place in the menu of the COMTRAXX® device under **Menu > Settings > Interface > Modbus**.

- Configure the mode of the Modbus RTU interface on the COMTRAXX® device (Factory setting: Master).
- If "Slave" is selected, the following parameters must be set:
 - The COMTRAXX® device must be assigned its own address. It can then be reached under this address via Modbus RTU.
 - "Send control commands" can be activated. In this way, control commands can be sent to BMS devices (factory setting: Off).

8 SNMP



The SNMP function is only active with function module "Interfaces".

8.1 Data access using SNMP

The COMTRAXX® device makes all measured values of the Bender system available via the SNMP interface. The SNMP versions V1, V2c and V3 are supported. The trap function can also be used. When an event occurs in the system, a message is automatically generated and sent to the SNMP manager. Up to 3 receivers can be configured.

8.2 Device assignment for SNMP

To use the SNMP function "Traps" or the individual texts from the COMTRAXX® application, the Bender MIB V2 must be used. It provides these functions. In addition, it is necessary to generate a device assignment for the SNMP image. There, the address of the device on the SNMP side is defined. This can be done automatically or configured individually.

The configuration is done at  **> Device management > Device assignment > SNMP**. There, the MIB files are also available for download.

9 MQTT



The MQTT function is only active with function module "Interfaces".

9.1 Data access via MQTT

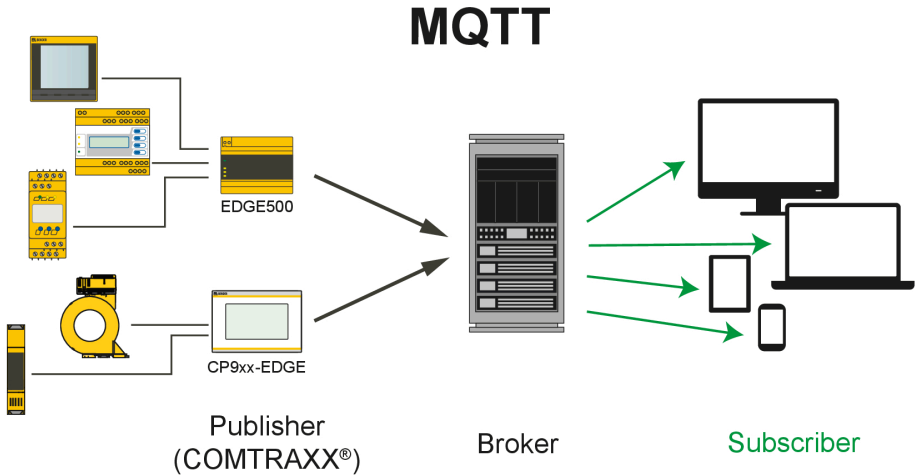


Figure 9-1: Overview of the MQTT principle

The COMTRAXX® device provides all measured values from the Bender system on the MQTT interface. The "Quality of Service" levels (QoS) 0...2 are supported.

9.2 Measured value assignment for MQTT

The MQTT measured value assignments are configured under

 **Tools > Device management > Device mapping > MQTT.**

Up to 255 measured values can be selected. The measured values and their properties can be output individually as a topic or summarised in a JSON structure.

9.3 Connection settings

Device >  Menu > Settings > Interface > MQTT

Menu item	Setting range		Remarks
Aktiviere	off/on		
IP address	xxx.xxx.xxx.xxx		
Port	1...65535		
Repetition interval	off		Period after which all values are sent, even if there has been no change. Factory setting: off
	on	15, 30, 60 minutes, 24 h	
Status	disconnected connected		
Client-ID	xxx		Individual MQTT client ID
QoS level ¹⁾	0...2		0 = At most once 1 = At least once 2 = Exactly once
Export language	deutsch, english, francais		Texts for measured value descriptions
Authentication	off		
	on	User	
		Password	
TLS	off		
	on	Managing MQTT certificates	 > Service > Certifikate settings
		Use uploaded CA certificate	off/on (format: *.pem)
		Use uploaded client certificate	off/on (format *.pem)
Will	off		
	on	Will Retain	
		Will Topic	
		Will Message	

1) QoS (Quality of Service)

0: Publisher sends the message once. No response is expected from the broker ("fire and forget").

1: Publisher sends the message once and repeats the delivery until an acknowledgement or the command to end the message is received from the broker ("acknowledged delivery").

2: Two-level acknowledgement of delivery The publisher only sends the message once a handshake has taken place with the broker. The broker confirms delivery of the message ("assured delivery").

10 PROFINET

PROFINET is supported from COMTRAXX® version V5.1.0 and higher.



Function is only active with function module "PROFINET".

All measured values and alarm states in the system are made available via PROFINET. These can then be recorded and processed in a PLC or visualisation system. The integration into the respective PLC or visualisation system is done via the provided GSDML file.

In the COMTRAXX® device, only a device assignment is required to allocate the required data to the available 511 PROFINET slots. The COMTRAXX® device is integrated into the PROFINET system as an IO device.

10.1 Configuration of the PROFINET interface

The PROFINET interface is configured in the menu of the COMTRAXX® device at

Menu > Settings > Interface > PROFINET.

- Configure status of PROFINET on the COMTRAXX® device (factory setting: PROFINET off)
- Configure PROFINET device names (this can also be done via a PLC or similar system)
- Configuring the Ethernet interface (using a GSDML file)

The GSDML file is available in the download area of our homepage at

<https://www.bender.de/en/service-support/download-area/> (Search term there: EDGE500)

10.2 Device assignment for PROFINET

To make the required measured values or alarm states available via PROFINET, a device assignment must be generated for the PROFINET image. The device assignment defines on which PROFINET slot the respective measuring channel appears. The device assignment can either be done automatically or configured individually. A total of 511 slots are available, which can access all measuring channels in the system.

Configuration is done at

 **Tools > Device management > Device assignment > PROFINET.**



If no device assignment is defined for a slot, the COMTRAXX® device will generate a diagnostic alarm when querying this slot. In addition, the data status (IO provider data) of the input data will be set to invalid!

10.3 Data modules

The following data modules can be applied to the available 511 slots in the respective PLC or similar system. The various data modules define which data is to be read via a slot. For each data module, it is also possible to set in the respective PLC or similar system whether a process alarm is to be generated. The process alarm is triggered when the respective assigned measuring channel reports an active alarm. By default, this setting is disabled in the PLCs or similar systems.



If no data is available for a slot, the output is 0xFF.

Data module	Format	Comment/Unit
Measured value	Float32	Measured value of the measuring channel as floating point number (IEEE754) with 32 bits
Measuring channel structure (Complete measuring channel as a structure with 26 bytes)	UINT32	Time stamp in s as 32-bit unsigned integer (UTC)
	UINT16	Decimal places of the time stamp in ms as 16-bit unsigned integer
	INT16	Time stamp UTC Offset in minutes as 16-bit integer
	UINT32	Alarm time stamp in s as 32-bit unsigned integer (UTC)
	UINT16	Decimal places of the alarm time stamp in ms as 16-bit unsigned integer
	INT16	Alarm time stamp UTC Offset in minutes as 16-bit-integer
	Float 32	Measured value of the measuring channel as floating point number (IEEE754) with 32 bits
	UINT16	Description as 16-bit unsigned integer (see Channel descriptions for the process image)
	UINT8	Alarm state as 8-bit unsigned integer 0 = No alarm 1 = Prewarning 2 = Error 3 = Reserved 4 = Warning 5 = Alarm
	UINT8	Unit as 8-bit unsigned integer (see R&U = Range and unit)
	UINT8	Value range as 8-bit unsigned integer 0 = Actual value 1 = Actual value is lower < 2 = Actual value is higher > 3 = Invalid value
	UINT8	Test state as 8-bit unsigned integer 0 = None 1 = Intern 2 = Extern
Alarm state	UINT8	Alarm state as 8-bit unsigned integer 0 = No alarm 1 = Prewarning 2 = Error 3 = Reserved 4 = Warning 5 = Alarm

10.4 Example of a data query

Example: Query measuring channel of an iso685-D

The iso685-D is connected to the COMTRAXX® device via BCOM. Measuring channel 3 (leakage capacitance C_{θ}) is to be made available on slot 13 in order to be able to read it out via PROFINET.

In order for the required measuring channel to be read via PROFINET, it only has to be included in the device assignment. To do this, open the PROFINET device assignment of the COMTRAXX® device

 **Tools > Device management > Device assignment > PROFINET**

and click on the "Add entry" button. Select slot and channel in the pop-up dialogue and confirm with "Ok".

The measuring channel now appears in the table and can be accepted with the "Save changes" button. The configuration of the COMTRAXX® device is now complete and the measuring channel can be read on slot 13.

11 Troubleshooting

11.1 Malfunctions

If the device causes malfunctions in the connected networks, please refer to this manual.

11.1.1 What should be checked?

Check whether

- the device is supplied with the correct supply voltage U_S .
- the BMS bus cable is correctly connected and terminated (120 Ω).
- the BMS address is set correctly.
- the BCOM address is set correctly.
- the Ethernet settings are correct.

11.1.2 Frequently asked questions

How do I access the device if the address data are unknown?

1. Connect the device directly to a PC using a patch cable
2. Activate the DHCP function on the PC.
3. Wait around one minute.
4. Access is now possible using the following pre-defined IP address:
ETH1: 169.254.0.1 | **ETH2:** 169.254.0.2
5. Now set the new address data.



Document the new settings as a PDF file using the "Document device" function. Also use the "Export backup" function to save all device settings (see Chapter: "Device features", page 11).

Frequently asked questions on the Internet

FAQs on many Bender devices can be found at:

["www.bender.de/en/ > Service & Support > Fast assistance"](http://www.bender.de/en/>Service%20Support%20Fast%20assistance)

11.2 Maintenance, Cleaning

Maintenance

The device does not contain any parts that require maintenance.

Cleaning

The device may only be cleaned using a dry cloth.

12 Technical data

12.1 Tabular data

()* = Factory setting

Insulation coordination in acc. with IEC 60664-1/IEC 60664-3

Rated voltage	AC 50 V
Overvoltage category	II
Pollution degree	2
Protective separation (reinforced insulation) between	(A1/+, A2/-) - [(X1), (X2), (X3), (X5)]

i Overvoltage category II and pollution degree 2 are related to the **relay contacts**. Further insulation coordination takes place based on functional separation.

Supply voltage

Connections	A1/+. A2/-
Supply voltage U_s	DC 24 V
Range U_s	DC 18...30 V
Protection class Power supply unit	2 or 3
Permissible ripple	5 %
Typical power consumption	≤ 3.5 W
Max. power consumption	≤ 10.5 W
Inrush current (< 5 ms)	< 1.5 A
Maximum cable length when supplied via B94053111 (DC 24 V power supply unit 1.75 A)	
0.28 mm ²	75 m
0.5 mm ²	130 m
0.75 mm ²	200 m
1.5 mm ²	400 m
2.5 mm ²	650 m

i The specified maximum power consumption is only reached if the maximum permissible power is drawn from both USB ports, all power components (such as relays) are activated, and the processor is operating at full capacity.

Indications

LEDs	
ON	Operation indicator
ETHERNET 1/2	Data traffic ETH1...2
NFC	<i>In preparation</i>
RS485 1	Data traffic RS-485 interface 1
RS485 2	Data traffic RS-485 interface 2

Memory

Number of data points for "third-party devices" on the Modbus TCP and Modbus RTU	50
Function modul "Engineering"	
Individual texts	Unlimited number of texts each with 100 characters
E-mail configurations and device failure monitoring	Max. 250 entries
Number of data loggers	30
Number of data points per data logger	10,000
Number of entries in the history memory	20,000

Visualisation (Function module "Live view")

Number of dashboards	50
Background image size	Max. 3 MB

Interfaces

RJ45 (X6...7)

Ethernet	
Connection	2 x RJ45
Cable	Shielded, min. Cat. 5
Cable length	< 100 m
Data rate	10/100/1000 MBit/s, autodetect
HTTP mode	HTTP/HTTPS (HTTP)*
DHCP	On/off (off)*
t_{off} (DHCP)	5...60 s (30 s)*
IP address	

Ethernet

First IP address: freely configurable nnn.nnn.nnn.nnn	ETH1 (192.168.0.254)* ETH2 (10.0.0.254)*
Second fixed IP address (e.g. for commissioning)	ETH1 (169.254.0.1) ETH2: 169.254.0.2
Netmask	nnn.nnn.nnn.nnn (255.255.0.0)*
Protocols (depending on the selected function module)	TCP/IP, Modbus TCP, Modbus RTU, MQTT, PROFINET, DHCP, SMTP, NTP

BCOM

Interface/protocol	ETH1 / BCOM
BCOM system name	(SYSTEM)*
BCOM subsystem address	1...255 (1)*
BCOM device address	0...255 (0)*

Modbus TCP

Interface/protocol	ETH1...2 / Modbus TCP
Client operating mode	Client for assigned Bender devices and "third-party devices"
Server operating mode	Server for access to process image and for Modbus control commands
Parallel data access from different clients	Max. 25
Bender Modbus image	V1, V2 (V2)*

PROFINET (Function module „PROFINET“)

Interface/protocol	ETH1...2 / PROFINET
Operating mode	Slave (IO device)
Slots for transferring measured values	511

SNMP (Function module „Interfaces“)

Interface/protocol	ETH1...2 / SNMP
Versions	1, 2c, 3
Supported devices	Queries to all devices (channels) possible
Trap support	Yes

MQTT (Function module „Interfaces“)

Interface/protocol	ETH1...2 / MQTT
Operating mode	Publisher (provides data for brokers)
Slots for transferring measured values	255

RS-485 (X5)

BMS bus (internal)

Interface/protocol	RS-485/BMS internal
Operating mode	Master/slave (master)*
Baud rate	9.6 kBaud
Cable length	≤ 1200 m
Cable	Shielded, one end of shield connected to PE
Cable recommended	CAT6/CAT7 min. AWG23
Cable alternatively	Twisted pair, J-Y (St) Y min. 2x0.8
Connection	X5 (RS2A, RS2B)
Connection type	See connection "Push-wire terminal B"
Terminating resistor	120 Ω (0.25 W), can be switched on via COMTRAXX® software
Device address, internal BMS bus	1...150 (1)*

Modbus RTU

Interface/protocol	RS-485/Modbus RTU
Operating mode	Master/slave (master)*
Baud rate	9.6...57.6 kBaud
Cable length	Depending on the baud rate
9.6 kBaud	< 1200 m
19.2 kBaud	< 1000 m
38.4 kBaud	< 800 m
57.6 kBaud	< 800 m
Cable	Shielded, one end of shield connected to PE
Cable recommended	CAT6/CAT7 min. AWG23
Cable alternatively	Twisted pair, J-Y (St) Y min. 2x0.8
Connection	X5 (RS1A, RS1B)
Connection type	See connection "Push-wire terminal B"

Modbus RTU

Terminating resistor	120 Ω (0.25 W), can be switched on via CONTRAXX® software
Supported Modbus RTU slave addresses	2...247

USB (X8...9)

Number	2
Connection type	USB-C
Operating mode	USB-2.0-Host (5 V, 500 mA)
Data rate	480 Mbit/s
Cable length	< 3 m

Digital inputs (X4)

Number	8
Galvanic separation	Yes
Maximum cable length	< 1000 m
Operating mode	Selectable for each input: high-active or low-active
Factory setting	High-active
Voltage range (high)	DC 12...30 V
Voltage range (low)	DC 0...2 V
Max. current per channel (at AC/DC 30 V)	8 mA
Connection plug-in terminal	(1-1) (2-2) (3-3) ... (8-8)

Switching elements (X1...3)

For UL applications: Intended use	General purpose relay
Number of changeover contacts	3
Voltage connected to the relay	SELV
Rated operating voltage	DC 24 V
Rated operating current	8 A
Operating principle	N/C operation N/O operation
Function	Programmable
Electrical endurance under rated operating conditions	10,000 operating cycles
Contact data acc. to IEC 60947-5-1	

Utilisation category	AC-13 / AC-14 / DC-12
Rated operational voltage	AC 24 V / AC 24 V / DC 24 V
Rated operational current	AC 2 A / AC 2 A / DC 2 A
Minimum contact load (reference specification of the relay manufacturer)	10 mA / 12 V DC
Connection plug-in terminal	K1 NO K1 COM K1 NC K2 NO K2 COM K2 NC K3 NO K3 COM K3 NC

Overview: Used ports

53	DNS (UDP/TCP)
67, 68	DHCP (UDP)
80	HTTP (TCP)
123	NTP (UDP)
161	SNMP (UDP)
162	SNMP TRAPS (UDP)
443	HTTPS (TCP)
502	MODBUS (TCP)
4840	OPCUA (TCP)
5353	MDNS (UDP)
48862	BCOM (UDP)

Environment / EMC

EMC	EN 61326-1 Table 1 - basic electromagnetic environment EN 61326-1 Table 2 - industrial electromangnetic environment IEC 62974-1:2024-08 Ed. 2.0 Clause 6.7, 7.3 Class 1
Electromagnetic environment	Other than residential environments, CISPR 11:2015/ AMD1:2016/AMD2:2019, Group 1, Class A Residential environments, CISPR 11:2015/AMD1:2016/ AMD2:2019, Group 1, Class B

Ambient temperatures

Operating temperature	-25...+55 °C
Transport	-40...+85 °C
Long-term storage	-25...+70 °C
Operating altitude	≤ 2000 m AMSL

Classification of climatic conditions acc. to IEC 60721

Stationary use (IEC 60721-3-3)	3K22
Transport (IEC 60721-3-2)	2K11
Long-term storage (IEC 60721-3-1)	1K22

Mechanical conditions acc. to IEC 60721

Stationary use (IEC 60721-3-3)	3M11
Transport (IEC 60721-3-2)	2M4
Long-term storage (IEC 60721-3-1)	1M12

Device connections

Push-wire terminal A (A1/+, A2/-)

Conductor sizes	AWG 24...12
Stripping length	10 mm
Rigid/flexible	0.2...2.5 mm ²
Flexible with ferrule with/without plastic sleeve	0.25...2.5 mm ²
Multiple conductor, flexible with TWIN ferrule with plastic sleeve	0.5...1.5 mm ²

Push-wire terminal B (X1, X2, X3, X4, X5)

For UL applications

Use copper lines only.	
Minimum temperature range of the cable to be connected to the terminals	100 °C
Conductor sizes X1, X2, X3	AWG 16
Conductor sizes X4, X5	AWG 24...16
Conductor sizes	AWG 24...16
Stripping length	10 mm
Rigid/flexible	0.2...1.5 mm ²
Flexible with ferrule without plastic sleeve	0.2...1.5 mm ²
Flexible with ferrule with plastic sleeve	0.2...1.5 mm ²

Other

Operating mode	Continuous operation
Mounting position	Front-orientated, air must pass through cooling slots vertically
Degree of protection, internal components (IEC 60529)	IP30

Degree of protection, terminals (IEC 60529)	IP20
Snap-on mounting on a DIN rail	IEC 60715
Screw mounting	3 x M4
Type of enclosure	J460
Enclosure material	Polycarbonate
Flammability class	UL94V-0
Dimensions (W x H x D)	107.5 x 93 x 62.9 mm
Weight	≤ 240 g

(*) = Factory setting

12.2 Standards, approvals and certifications



EU Declaration of Conformity

The full text of the EU Declaration of Conformity is available via:

https://www.bender.de/fileadmin/content/Products/CE/CEKO_EDGE500.pdf

UKCA Declaration of Conformity

The full text of the UKCA Declaration of Conformity is available via:

https://www.bender.de/fileadmin/content/Products/UKCA/UKCA_EDGE500.pdf

12.3 Ordering information

Device

Type	Application	Supply voltage U_S	Power consumption	Art. No.
EDGE500IP	- Condition monitor with gateway functionality - Integration and provision of Bender device data	DC 24 V	≤ 3.5 W	B95061250

Function modules

Function module (Software license)	Function	Art. No.
Function module Interfaces	Interfaces Modbus TCP / RTU: Full access to data Modbus TCP / RTU: Control commands BMS SNMP MQTT Integrating third-party Modbus devices (2,000 data points)	B75061030
Function module Engineering	Configuration System overview Parameter setting Backups Documentation Individual texts E-mail notifications Device failure monitoring History memory of the device Data logger Virtual devices	B75061031
Function module Live view	Visualisation Visualisation / editor Alarm addresses / test addresses	B75061032
Function module PROFINET	Communication PROFINET 511 Data points (Available from version V5.1.0)	B75061033

12.4 Documentation revision history

Date	Document version	Valid from software version	State/Changes
04.2025	00	5.0.x	First edition
07.2025	01		<i>Editorial revision</i> Interfaces adjustment
12.2025	02		<i>Correction</i> Ordering information: External power supply unit
09.2026	03	5.1.x	<i>Editorial revision</i> Entire document <i>Added</i> "PROFINET" function module; integration of third-party devices; UL and LR approvals



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